

TDRV009-SW-82

Linux Device Driver

High Speed Synch/Asynch Serial Interface

Version 2.1.x

User Manual

Issue 2.1.1

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TDRV009-SW-82

Linux Device Driver

High Speed Synch/Asynch Serial Interface

Supported Modules:

- TPMC363
- TPMC863
- TCP863
- TAMC863
- TPCE863
- TMPE863

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1 Introduction

The TDRV009-SW-82 Linux device driver allows the operation of the TDRV009 compatible devices conforming to the Linux I/O system specification.

The TDRV009-SW-82 device driver supports the following features:

- setup and configure serial channels
- send and receive data buffers (character oriented)
- read and write onboard registers directly
- read and write access to onboard EEPROM
- control handshake lines
- wait for interrupts

The TDRV009-SW-82 supports the modules listed below:

TPMC863	4 Channel High Speed Synch/Asynch Serial Interface	PMC
TPMC363	4 Channel High Speed Synch/Asynch Serial Interface	PMC, Conduction Cooled
TCP863	4 Channel High Speed Synch/Asynch Serial Interface	CompactPCI
TAMC863	4 Channel High Speed Synch/Asynch Serial Interface	Advanced Mezzanine Card
TPCE863	4 Channel High Speed Synch/Asynch Serial Interface	Standard PCI-Express
TMPE863	3 Channel High Speed Synch/Asynch Serial Interface	PCIe Mini Card

In this document all supported modules and devices will be called TDRV009. Specials for a certain device will be advised.

To get more information about the features and use of supported devices it is recommended to read the manuals listed below.

TPMC863 (or compatible) User Manual
TMPE863 (or compatible) User Manual

2 Installation

Following files are located on the distribution media:

Directory path 'TDRV009-SW-82':

TDRV009-SW-82-2.1.0.pdf	This manual in PDF format
TDRV009-SW-82-SRC.tar.gz	GZIP compressed archive with driver source code
ChangeLog.txt	Release history
Release.txt	Release information

The GZIP compressed archive TDRV009-SW-82-SRC.tar.gz contains the following files and directories:

Directory path 'tdrv009':

tdrv009.c	TDRV009 device driver source
tdrv009def.h	TDRV009 driver include file
commCtrl.h	Include file for controller chip
tdrv009.h	TDRV009 include file for driver and application
makenode	Script to create device nodes on the file system
Makefile	Device driver make file
COPYING	Copy of the GNU Public License (GPL)
example/tdrv009exa.c	Example application
example/Makefile	Example application make file
api/tdrv009api.c	Application Programming Interface source
api/tdrv009api.h	Application Programming Interface header
include/config.h	Driver independent library header file
include/tpmodule.h	Driver and kernel independent library header file
include/tpmodule.c	Driver and kernel independent library source file

In order to perform an installation, extract all files of the archive TDRV009-SW-82-SRC.tar.gz to the desired target directory. The command 'tar -xzvf TDRV009-SW-82-SRC.tar.gz' will extract the files into the local directory.

- Login as *root* and change to the target directory
- Copy tdrv009.h to */usr/include*

2.1 Build and install the Device Driver

- Login as *root*
- Change to the target directory
- To create and install the driver in the module directory */lib/modules/<version>/misc* enter:
 - # make install**
- To update the device driver's module dependencies, enter:
 - # depmod -aq**

2.2 Uninstall the Device Driver

- Login as *root*
- Change to the target directory
- To remove the driver from the module directory */lib/modules/<version>/misc* enter:

make uninstall

2.3 Install Device Driver into the running Kernel

- To load the device driver into the running kernel, login as root and execute the following commands:

modprobe tdrv009drv
- After the first build or if you are using dynamic major device allocation it is necessary to create new device nodes on the file system. Please execute the script file *makenode* to do this. If your kernel has enabled a device file system (devfs or sysfs with udev) then you have to skip running the *makenode* script. Instead of creating device nodes from the script the driver itself takes creating and destroying of device nodes in its responsibility.

sh makenode

On success the device driver will create a minor device for each compatible channel found. The first channel of the first TDRV009 device can be accessed with device node */dev/tdrv009_0*, the second channel with device node */dev/tdrv009_1* and so on. The assignment of device nodes to physical TDRV009 devices depends on the search order of the PCI bus driver.

2.4 Remove Device Driver from the running Kernel

- To remove the device driver from the running kernel login as root and execute the following command:

modprobe -r tdrv009drv

If your kernel has enabled devfs or sysfs (udev), all */dev/tdrv009_x* nodes will be automatically removed from your file system after this.

Be sure that the driver is not opened by any application program. If opened you will get the response ``tdrv009drv: Device or resource busy`` and the driver will still remain in the system until you close all opened files and execute *modprobe -r* again.

2.5 Change Major Device Number

This paragraph is only for Linux kernels without DEVFS installed.

The TDRV009 device driver uses dynamic allocation of major device numbers per default. If this isn't suitable for the application it's possible to define a major number for the driver.

To change the major number edit the file `tdrv009def.h`, change the following symbol to appropriate value and enter `make install` to create a new driver.

TDRV009_MAJOR	Valid numbers are in range between 0 and 255. A value of 0 means dynamic number allocation.
---------------	---

Example:

```
#define TDRV009_MAJOR 122
```

Be sure that the desired major number is not used by other drivers. Please check `/proc/devices` to see which numbers are free.

Keep in mind that it is necessary to create new device nodes if the major number for the TDRV009 driver has changed and the `makenode` script is not used.

3 API Documentation

3.1 General Functions

3.1.1 tdrv009Open

NAME

tdrv009Open – opens a device

SYNOPSIS

```
TDRV009_HANDLE tdrv009Open
(
    char      *DeviceName
)
```

DESCRIPTION

Before I/O can be performed to a device, a device descriptor must be opened by a call to this function.

PARAMETERS

DeviceName

This parameter points to a null-terminated string that specifies the name of the device. The first TDRV009 channel device is named “/dev/tdrv009_0” the second channel is named “/dev/tdrv009_1” and so on.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE    hdl;

/*
** open the specified device
*/
hdl = tdrv009Open("/dev/tdrv009_0");
if (hdl == NULL)
{
    /* handle open error */
}
```


RETURNS

A device handle, or NULL if the function fails. An error code will be stored in *errno*.

ERROR CODES

The error codes are stored in *errno*.

The error code is a standard error code set by the I/O system.

3.1.2 tdrv009Close

NAME

tdrv009Close – closes a device

SYNOPSIS

```
TDRV009_STATUS tdrv009Close
(
    TDRV009_HANDLE    hdl
)
```

DESCRIPTION

This function closes previously opened devices.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE    hdl;
TDRV009_STATUS    result;

/*
** close the device
*/
result = tdrv009Close(hdl);
if (result != TDRV009_OK)
{
    /* handle close error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified device handle is invalid

3.1.3 tdrv009GetPciInfo

NAME

tdrv009GetPciInfo – get information of the module PCI header

SYNOPSIS

```
TDRV009_STATUS tdrv009GetPciInfo
(
    TDRV009_HANDLE          hdl,
    TDRV009_PCIINFO_BUF    *pPciInfoBuf
)
```

DESCRIPTION

This function returns information of the module PCI header in the provided data buffer.

PARAMETERS

hdl

This argument specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pPciInfoBuf

This argument is a pointer to the structure TDRV009_PCIINFO_BUF that receives information of the module PCI header.

```
typedef struct
{
    unsigned short    vendorId;
    unsigned short    deviceId;
    unsigned short    subSystemId;
    unsigned short    subSystemVendorId;
    int               pciBusNo;
    int               pciDevNo;
    int               pciFuncNo;
} TDRV009_PCIINFO_BUF;
```

vendorId

PCI module vendor ID.

deviceId
PCI module device ID

subSystemId
PCI module sub system ID

subSystemVendorId
PCI module sub system vendor ID

pciBusNo
Number of the PCI bus, where the module resides.

pciDevNo
PCI device number

pciFuncNo
PCI function number

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
TDRV009_PCIINFO_BUF pciInfoBuf

/*
** get module PCI information
*/
result = tdrv009GetPciInfo( hdl, &pciInfoBuf );

if (result != TDRV009_OK)
{
    /* handle error */
}
```

RETURN VALUE

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified device handle is invalid

3.1.4 tdrv009GetBoardName

NAME

tdrv009GetBoardName – get Name of the board

SYNOPSIS

```
TDRV009_STATUS tdrv009GetBoardName
(
    TDRV009_HANDLE          hdl,
    char                    *pBoardName,
    int                     len
)
```

DESCRIPTION

This function returns the name of the hardware board to distinguish between the supported hardware modules and devices.

PARAMETERS

hdl

This argument specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pBoardName

This argument returns a null-terminated ASCII string describing the specific hardware module. The following boarding naming scheme is implemented:

Value	Description
"TPMC863"	TPMC863 Device
"TMPE863"	TMPE863 Device

len

This argument specifies the maximum length available for storing the board name.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
char                BoardName[40];

/*
** get board name
*/
result = tdrv009GetBoardName( hdl, &BoardName, 40 );

if (result == TDRV009_OK)
{
    printf("Board Name: %s\n", BoardName);
} else {
    /* handle error */
}
```

RETURN VALUE

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified device handle is invalid

3.2 Device Access Functions

3.2.1 tdrv009Write

NAME

tdrv009Write – Write data from a buffer to a specified device

SYNOPSIS

```
TDRV009_STATUS tdrv009Write
(
    TDRV009_HANDLE          hdl,
    char                    *pData,
    int                     nBytes
)
```

DESCRIPTION

This function attempts to write a data buffer to the specified TDRV009 channel. The user specifies a character buffer pointed to by *pData*. The argument *nBytes* specifies the length of the buffer. The function performs a non-blocking write operation, i.e. the function returns immediately after inserting the data into the transmit-queue.

PARAMETERS

hdl

This value specifies the device handle to the hardware channel retrieved by a call to the corresponding open-function.

pData

This argument points to a user supplied buffer. The data of the buffer will be transferred to the device.

nBytes

This parameter specifies the number of bytes to write.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;
unsigned char Data[100];

/*
** Send data on TDRV009 channel
*/
sprintf( (char*)Data, "Hello World" );

result = tdrv009Write (
                hdl,
                Data,
                strlen((char*)Data)
            );
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.2 tdrv009Read

NAME

tdrv009Read – Read data from device

SYNOPSIS

```
TDRV009_STATUS tdrv009Read
(
    TDRV009_HANDLE          hdl,
    char                    *pData,
    int                     nBytes
)
```

DESCRIPTION

This function attempts to read an input buffer from a TDRV009 channel. The argument *nBytes* specifies the length of the buffer. Available data (up to *nBytes* bytes) is copied into the user's buffer pointed to by *pData*. The function performs a blocking read operation, i.e. the function waits until data is available or the specified timeout expires (see *SetReadTimeout*).

PARAMETERS

hdl

This value specifies the device handle to the hardware channel retrieved by a call to the corresponding open-function.

pData

This argument points to a user supplied buffer where the received data will be stored.

nBytes

This parameter specifies the number of bytes to read.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;
unsigned char   Data[100];

/*
** Receive up to 100 data bytes on TDRV009 channel
*/
result = tdrv009Read (
                hdl,
                Data,
                100
            );
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.3 tdrv009SetOperationMode

NAME

tdrv009SetOperationMode – Configure Channel Operation Mode

SYNOPSIS

```
TDRV009_STATUS tdrv009SetOperationMode  
(  
    TDRV009_HANDLE          hdl,  
    TDRV009_OPERATION_MODE *pOperationMode  
)
```

DESCRIPTION

This function configures the channel's operation mode.

A call to this function must be done prior to any communication operation, because after driver startup, the channel's transceivers are disabled.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pOperationMode

This argument points to a TDRV009_OPERATION_MODE_STRUCT structure. It is necessary to completely initialize the structure. This can be done by calling the API function tdrv009GetOperationMode described below.

```

typedef struct
{
    TDRV009_COMM_TYPE           CommType;
    TDRV009_TRANSCEIVER_MODE    TransceiverMode;
    TDRV009_ENABLE_DISABLE      Oversampling;
    TDRV009_BRGSOURCE           BrgSource;
    TDRV009_TXCSOURCE           TxClkSource;
    unsigned int                 TxClkOutput;
    TDRV009_RXCSOURCE           RxClkSource;
    TDRV009_CLKMULTIPLIER       ClockMultiplier;
    unsigned int                 Baudrate;
    unsigned char                ClockInversion;
    unsigned char                Encoding;
    TDRV009_PARITY               Parity;
    int                           Stopbits;
    int                           Databits;
    TDRV009_ENABLE_DISABLE      UseTermChar;
    char                          TermChar;
    TDRV009_ENABLE_DISABLE      HwHs;
    TDRV009_CRC                  Crc;
} TDRV009_OPERATION_MODE_STRUCT;

```

CommType

This parameter describes the general communication type for the specific channel. Possible values are:

Value	Description
TDRV009_COMMTYPE_ASYNC	Asynchronous communication
TDRV009_COMMTYPE_HDLC_ADDR0	Standard HDLC communication without address recognition. Used for synchronous communication.
TDRV009_COMMTYPE_HDLC_TRANSP	Extended Transparent mode. No protocol processing, channel works as simple bit collector.

TransceiverMode

This parameter describes the transceiver mode of the programmable multi-protocol transceivers. Possible values are:

Value	Description
TDRV009_TRNSCVR_NOT_USED	Default V.11
TDRV009_TRNSCVR_RS530A	EIA-530A (V.11 / V.10)
TDRV009_TRNSCVR_RS530	EIA-530 (V.11), also suitable for RS422
TDRV009_TRNSCVR_X21	X.21 (V.11)
TDRV009_TRNSCVR_V35	V.35 (V.35 / V.28)
TDRV009_TRNSCVR_RS449	EIA-449 (V.11)
TDRV009_TRNSCVR_V36	V.36 (V.11)
TDRV009_TRNSCVR_RS232	EIA-232 (V.28)
TDRV009_TRNSCVR_V28	V.28 (V.28)
TDRV009_TRNSCVR_NO_CABLE	High impedance

Oversampling

This parameter enables or disables 16-times oversampling, used for asynchronous communication. For communication with standard UARTs it is recommended to enable this feature. Valid values are:

Value	Description
TDRV009_DISABLED	The 16-times oversampling is not used.
TDRV009_ENABLED	The 16-times oversampling is used.

BrgSource

This parameter specifies the frequency source used as input to the BRG (Baud Rate Generator). Valid values are:

Value	Description
TDRV009_BRGSRC_XTAL1	XTAL1 oscillator is used for BRG input
TDRV009_BRGSRC_XTAL2	XTAL2 oscillator is used for BRG input
TDRV009_BRGSRC_XTAL3	XTAL3 oscillator is used for BRG input
TDRV009_BRGSRC_RXCEXTERN	External clock at RxC input used for BRG input
TDRV009_BRGSRC_TXCEXTERN	External clock at TxC input used for BRG input

TxCkSource

This parameter specifies the frequency source used as input to the transmit engine. Valid values are:

Value	Description
TDRV009_TXCSRC_BRG	Baud Rate Generator output used for Tx clock
TDRV009_TXCSRC_BRGDIV16	BRG output divided by 16 used for Tx clock
TDRV009_TXCSRC_RXCEXTERN	External clock at RxC input used for Tx clock
TDRV009_TXCSRC_TXCEXTERN	External clock at TxC input used for Tx clock
TDRV009_TXCSRC_DPLL	DPLL output used for Tx clock

TxClockOutput

This parameter specifies which output lines are used to output the transmit clock, e.g. for synchronous communication. The given values can be binary OR'ed. Valid values are:

Value	Description
TDRV009_TXCOUT_TXC	Transmit clock available at TxC output line
TDRV009_TXCOUT_RTS	Transmit clock available at RTS output line

RxClockSource

This parameter specifies the frequency source used as input to the receive engine. Valid values are:

Value	Description
TDRV009_RXCSRC_BRG	Baud Rate Generator output used for Rx clock
TDRV009_RXCSRC_RXCEXTERN	External clock at RxC input used for Rx clock
TDRV009_RXCSRC_DPLL	DPLL output used for Rx clock

ClockMultiplier

This parameter specifies the multiplier used for BRG clock input. Valid values are:

Value	Description
TDRV009_CLKMULT_X1	Clock multiplier disabled
TDRV009_CLKMULT_X4	Selected input clock is multiplied by 4

Baudrate

This parameter specifies the desired frequency to be generated by the Baud Rate Generator (BRG), which can be used as clock input signal. The value is derived from the selected clocksource. Please note that only specific values depending on the selected oscillator are valid. This frequency is internally multiplied by 16, if oversampling shall be used.

ClockInversion

This parameter specifies the inversion of the transmit clock and/or the receive clock. This value can be binary OR'ed. Possible values are:

Value	Description
TDRV009_CLKINV_NONE	no clock inversion
TDRV009_CLKINV_TXC	transmit clock is inverted
TDRV009_CLKINV_RXC	receive clock is inverted

Encoding

This parameter specifies the data encoding used for communication. Valid values are:

Value	Description
TDRV009_ENC_NRZ	NRZ data encoding
TDRV009_ENC_NRZI	NRZI data encoding
TDRV009_ENC_FM0	FM0 data encoding
TDRV009_ENC_FM1	FM1 data encoding
TDRV009_ENC_MANCHESTER	Manchester data encoding

Parity

This parameter specifies the parity bit generation used for asynchronous communication. Valid values are:

Value	Description
TDRV009_PAR_DISABLED	No parity generation is used.
TDRV009_PAR_EVEN	EVEN parity bit
TDRV009_PAR_ODD	ODD parity bit
TDRV009_PAR_SPACE	SPACE parity bit (always insert '0')
TDRV009_PAR_MARK	MARK parity bit (always insert '1')

Stopbits

This parameter specifies the number of stop bits to use for asynchronous communication. Possible values are 1 or 2.

Databits

This parameter specifies the number of data bits to use for asynchronous communication. Possible values are 5 to 8.

UseTermChar

This parameter enables or disables the usage of a termination character for asynchronous communication. Valid values are:

Value	Description
TDRV009_DISABLED	A termination character is not used.
TDRV009_ENABLED	A termination character is used.

TermChar

This parameter specifies the termination character. After receiving this termination character, the communication controller will forward the received data packet immediately to the host system and use a new data packet for further received data. Any 8bit value may be used for this parameter.

HwHs

This parameter enables or disables the hardware handshaking mechanism using RTS/CTS. Valid values are:

Value	Description
TDRV009_DISABLED	Hardware handshaking is not used.
TDRV009_ENABLED	Hardware handshaking is used.

Crc

This parameter is a structure describing the CRC checking configuration.

```
typedef struct
{
    TDRV009_CRC_TYPE           Type;
    TDRV009_ENABLE_DISABLE    RxChecking;
    TDRV009_ENABLE_DISABLE    TxGeneration;
    TDRV009_CRC_RESET         ResetValue;
} TDRV009_CRC;
```

Type

This parameter describes the CRC type to be used. Possible values are:

Value	Description
TDRV009_CRC_16	16bit CRC algorithm is used for checksum
TDRV009_CRC_32	32bit CRC algorithm is used for checksum

RxChecking

This parameter enables or disables the receive CRC checking. Possible values are:

Value	Description
TDRV009_DISABLED	CRC checking will not be used
TDRV009_ENABLED	CRC checking will be used

TxGeneration

This parameter enables or disables the transmit CRC generation. Possible values are:

Value	Description
TDRV009_DISABLED	A CRC checksum will be generated
TDRV009_ENABLED	A CRC checksum will not be generated

ResetValue

This parameter describes the reset value for the CRC algorithm. Possible values are:

Value	Description
TDRV009_CRC_RST_FFFF	CRC reset value will be 0xFFFF
TDRV009_CRC_RST_0000	CRC reset value will be 0x0000

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;
TDRV009_OPERATION_MODE_STRUCT OperationMode;

/*-----
   Configure channel for Async / RS232 / 115200bps
   -----*/
OperationMode.CommType           = TDRV009_COMMTYPE_ASYNC;
OperationMode.TransceiverMode    = TDRV009_TRNSCVR_RS232;
OperationMode.Oversampling       = TDRV009_ENABLED;
OperationMode.BrgSource          = TDRV009_BRGSRC_XTAL1;
OperationMode.TxClockSource      = TDRV009_TXCSRC_BRG;
OperationMode.TxClockOutput      = 0;
OperationMode.RxClockSource      = TDRV009_RXCSRC_BRG;
OperationMode.ClockMultiplier   = TDRV009_CLKMULT_X1;
OperationMode.Baudrate           = 115200;
OperationMode.ClockInversion     = TDRV009_CLKINV_NONE;
OperationMode.Encoding           = TDRV009_ENC_NRZ;
OperationMode.Parity             = TDRV009_PAR_DISABLED;
OperationMode.Stopbits           = 1;
OperationMode.Databits           = 8;
OperationMode.UseTermChar        = TDRV009_DISABLED;
OperationMode.TermChar           = 0;
OperationMode.HwHs               = TDRV009_DISABLED;
OperationMode.Crc.Type           = TDRV009_CRC_16;
OperationMode.Crc.RxChecking     = TDRV009_DISABLED;
OperationMode.Crc.TxGeneration   = TDRV009_DISABLED;
OperationMode.Crc.ResetValue     = TDRV009_CRC_RST_FFFF;

result = tdrv009SetOperationMode(hdl, &OperationMode);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. A parameter inside the structure is invalid.
TDRV009_ERR_NOTSUP	Specified parameter (e.g. transceiver mode) is not supported by the hardware.

Other returned error codes are system error conditions.

3.2.4 tdrv009GetOperationMode

NAME

tdrv009GetOperationMode – Return Channel's current Operation Mode Configuration

SYNOPSIS

```
TDRV009_STATUS tdrv009GetOperationMode
(
    TDRV009_HANDLE          hdl,
    TDRV009_OPERATION_MODE *pOperationMode
)
```

DESCRIPTION

This function reads the channel's current operation mode configuration.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pOperationMode

This argument points to a TDRV009_OPERATION_MODE_STRUCT structure.

```

typedef struct
{
    TDRV009_COMM_TYPE           CommType;
    TDRV009_TRANSCEIVER_MODE   TransceiverMode;
    TDRV009_ENABLE_DISABLE     Oversampling;
    TDRV009_BRGSOURCE          BrgSource;
    TDRV009_TXCSOURCE          TxClkSource;
    unsigned int                TxClkOutput;
    TDRV009_RXCSOURCE          RxClkSource;
    TDRV009_CLKMULTIPLIER      ClockMultiplier;
    unsigned int                Baudrate;
    unsigned char               ClockInversion;
    unsigned char               Encoding;
    TDRV009_PARITY              Parity;
    int                          Stopbits;
    int                          Databits;
    TDRV009_ENABLE_DISABLE     UseTermChar;
    char                         TermChar;
    TDRV009_ENABLE_DISABLE     HwHs;
    TDRV009_CRC                 Crc;
} TDRV009_OPERATION_MODE_STRUCT;

```

CommType

This parameter describes the general communication type for the specific channel. Possible values are:

Value	Description
TDRV009_COMMTYPE_ASYNC	Asynchronous communication
TDRV009_COMMTYPE_HDLC_ADDR0	Standard HDLC communication without address recognition. Used for synchronous communication.
TDRV009_COMMTYPE_HDLC_TRANSP	Extended Transparent mode. No protocol processing, channel works as simple bit collector.

TransceiverMode

This parameter describes the transceiver mode of the programmable multi-protocol transceivers. Possible values are:

Value	Description
TDRV009_TRNSCVR_NOT_USED	Default V.11
TDRV009_TRNSCVR_RS530A	EIA-530A (V.11 / V.10)
TDRV009_TRNSCVR_RS530	EIA-530 (V.11), also suitable for RS422
TDRV009_TRNSCVR_X21	X.21 (V.11)
TDRV009_TRNSCVR_V35	V.35 (V.35 / V.28)
TDRV009_TRNSCVR_RS449	EIA-449 (V.11)
TDRV009_TRNSCVR_V36	V.36 (V.11)
TDRV009_TRNSCVR_RS232	EIA-232 (V.28)
TDRV009_TRNSCVR_V28	V.28 (V.28)
TDRV009_TRNSCVR_NO_CABLE	High impedance

Oversampling

This parameter enables or disables 16-times oversampling, used for asynchronous communication. For communication with standard UARTs it is recommended to enable this feature. Valid values are:

Value	Description
TDRV009_DISABLED	The 16-times oversampling is not used.
TDRV009_ENABLED	The 16-times oversampling is used.

BrgSource

This parameter specifies the frequency source used as input to the BRG (Baud Rate Generator). Valid values are:

Value	Description
TDRV009_BRGSRC_XTAL1	XTAL1 oscillator is used for BRG input
TDRV009_BRGSRC_XTAL2	XTAL2 oscillator is used for BRG input
TDRV009_BRGSRC_XTAL3	XTAL3 oscillator is used for BRG input
TDRV009_BRGSRC_RXCEXTERN	External clock at RxC input used for BRG input
TDRV009_BRGSRC_TXCEXTERN	External clock at TxC input used for BRG input

TxCkSource

This parameter specifies the frequency source used as input to the transmit engine. Valid values are:

Value	Description
TDRV009_TXCSRC_BRG	Baud Rate Generator output used for Tx clock
TDRV009_TXCSRC_BRGDIV16	BRG output divided by 16 used for Tx clock
TDRV009_TXCSRC_RXCEXTERN	External clock at RxC input used for Tx clock
TDRV009_TXCSRC_TXCEXTERN	External clock at TxC input used for Tx clock
TDRV009_TXCSRC_DPLL	DPLL output used for Tx clock

TxClockOutput

This parameter specifies which output lines are used to output the transmit clock, e.g. for synchronous communication. The given values can be binary OR'ed. Valid values are:

Value	Description
TDRV009_TXCOUT_TXC	Transmit clock available at TxC output line
TDRV009_TXCOUT_RTS	Transmit clock available at RTS output line

RxClockSource

This parameter specifies the frequency source used as input to the receive engine. Valid values are:

Value	Description
TDRV009_RXCSRC_BRG	Baud Rate Generator output used for Rx clock
TDRV009_RXCSRC_RXCEXTERN	External clock at Rx input used for Rx clock
TDRV009_RXCSRC_DPLL	DPLL output used for Rx clock

ClockMultiplier

This parameter specifies the multiplier used for BRG clock input. Valid values are:

Value	Description
TDRV009_CLKMULT_X1	Clock multiplier disabled
TDRV009_CLKMULT_X4	Selected input clock is multiplied by 4

Baudrate

This parameter specifies the desired frequency to be generated by the Baud Rate Generator (BRG), which can be used as clock input signal. The value is derived from the selected clocksource. Please note that only specific values depending on the selected oscillator are valid. This frequency is internally multiplied by 16, if oversampling shall be used.

ClockInversion

This parameter specifies the inversion of the transmit clock and/or the receive clock. This value can be binary OR'ed. Possible values are:

Value	Description
TDRV009_CLKINV_NONE	no clock inversion
TDRV009_CLKINV_TXC	transmit clock is inverted
TDRV009_CLKINV_RXC	receive clock is inverted

Encoding

This parameter specifies the data encoding used for communication. Valid values are:

Value	Description
TDRV009_ENC_NRZ	NRZ data encoding
TDRV009_ENC_NRZI	NRZI data encoding
TDRV009_ENC_FM0	FM0 data encoding
TDRV009_ENC_FM1	FM1 data encoding
TDRV009_ENC_MANCHESTER	Manchester data encoding

Parity

This parameter specifies the parity bit generation used for asynchronous communication. Valid values are:

Value	Description
TDRV009_PAR_DISABLED	No parity generation is used.
TDRV009_PAR_EVEN	EVEN parity bit
TDRV009_PAR_ODD	ODD parity bit
TDRV009_PAR_SPACE	SPACE parity bit (always insert '0')
TDRV009_PAR_MARK	MARK parity bit (always insert '1')

Stopbits

This parameter specifies the number of stop bits to use for asynchronous communication. Possible values are 1 or 2.

Databits

This parameter specifies the number of data bits to use for asynchronous communication. Possible values are 5 to 8.

UseTermChar

This parameter enables or disables the usage of a termination character for asynchronous communication. Valid values are:

Value	Description
TDRV009_DISABLED	A termination character is not used.
TDRV009_ENABLED	A termination character is used.

TermChar

This parameter specifies the termination character. After receiving this termination character, the communication controller will forward the received data packet immediately to the host system and use a new data packet for further received data. Any 8bit value may be used for this parameter.

HwHs

This parameter enables or disables the hardware handshaking mechanism using RTS/CTS. Valid values are:

Value	Description
TDRV009_DISABLED	Hardware handshaking is not used.
TDRV009_ENABLED	Hardware handshaking is used.

Crc

This parameter is a structure describing the CRC checking configuration.

```
typedef struct
{
    TDRV009_CRC_TYPE           Type;
    TDRV009_ENABLE_DISABLE    RxChecking;
    TDRV009_ENABLE_DISABLE    TxGeneration;
    TDRV009_CRC_RESET         ResetValue;
} TDRV009_CRC;
```

Type

This parameter describes the CRC type to be used. Possible values are:

Value	Description
TDRV009_CRC_16	16bit CRC algorithm is used for checksum
TDRV009_CRC_32	32bit CRC algorithm is used for checksum

RxChecking

This parameter enables or disables the receive CRC checking. Possible values are:

Value	Description
TDRV009_DISABLED	CRC checking will not be used
TDRV009_ENABLED	CRC checking will be used

TxGeneration

This parameter enables or disables the transmit CRC generation. Possible values are:

Value	Description
TDRV009_DISABLED	A CRC checksum will be generated
TDRV009_ENABLED	A CRC checksum will not be generated

ResetValue

This parameter describes the reset value for the CRC algorithm. Possible values are:

Value	Description
TDRV009_CRC_RST_FFFF	CRC reset value will be 0xFFFF
TDRV009_CRC_RST_0000	CRC reset value will be 0x0000

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE          hdl;
TDRV009_STATUS          result;
TDRV009_OPERATION_MODE_STRUCT  OperationMode;

/*-----
   Read Channel Operation Mode
   -----*/
result = tdrv009GetOperationMode(hdl, &OperationMode);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.5 tdrv009SetBaudrate

NAME

tdrv009SetBaudrate – Configure Transmission Rate

SYNOPSIS

```
TDRV009_STATUS tdrv009SetBaudrate
(
    TDRV009_HANDLE          hdl,
    int                     Baudrate
)
```

DESCRIPTION

This function sets up the transmission rate for the specific channel. This is done without changing the configuration set by `tdrv009SetOperationMode`. If async oversampling is enabled, the desired baudrate is internally multiplied by 16. It is important that this result can be derived from the selected clocksource. This function specifies the desired frequency which should be generated by the Baud Rate Generator (BRG).

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

Baudrate

This parameter specifies the baudrate which should be generated by the Baud Rate Generator. Be sure that the baudrate can be derived from the previously selected clock source.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;

/*-----
   Set baudrate to 14400bps
   -----*/
result = tdrv009SetBaudrate(hdl, 14400);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. The desired baudrate cannot be derived from the selected clock source.

Other returned error codes are system error conditions.

3.2.6 tdrv009SetReceiverState

NAME

tdrv009SetReceiverState – Enable/Disable the receiver

SYNOPSIS

```
TDRV009_STATUS tdrv009SetReceiverState
(
    TDRV009_HANDLE          hdl,
    int                     ReceiverState
)
```

DESCRIPTION

This function sets the channel's receiver either to active or inactive.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

ReceiverState

This parameter defines the new state of the receiver. Possible values are:

Value	Description
TDRV009_RCVR_ON	The receiver is enabled.
TDRV009_RCVR_OFF	The receiver is disabled.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;

/*-----
   Enable the receiver
   -----*/
result = tdrv009SetReceiverState(hdl, TDRV009_RCVR_ON);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified.

Other returned error codes are system error conditions.

3.2.7 tdrv009ClearRxBuffer

NAME

tdrv009ClearRxBuffer – Discard all received data

SYNOPSIS

```
TDRV009_STATUS tdrv009ClearRxBuffer
(
    TDRV009_HANDLE      hdl
)
```

DESCRIPTION

This function removes all received data from the channel's receive buffer, and flushes the hardware FIFO as well.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;

/*-----
   Clear receive buffer
   -----*/
result = tdrv009ClearRxBuffer( hdl );
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.8 tdrv009RtsSet

NAME

tdrv009RtsSet – Assert RTS Signal

SYNOPSIS

```
TDRV009_STATUS tdrv009RtsSet
(
    TDRV009_HANDLE          hdl
)
```

DESCRIPTION

This function asserts the RTS handshake signal line of the specific channel. This function is not available if the channel is configured for hardware handshaking.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;

/*-----
   Assert RTS
   -----*/
result = tdrv009RtsSet( hdl );
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_NOTSUP	The channel is in handshake mode, so this function is not allowed.
TDRV009_ERR_ACCESS	This function is not supported by the specific channel.

Other returned error codes are system error conditions.

3.2.9 tdrv009RtsClear

NAME

tdrv009RtsClear – De-Assert RTS Signal

SYNOPSIS

```
TDRV009_STATUS tdrv009RtsClear
(
    TDRV009_HANDLE          hdl
)
```

DESCRIPTION

This function de-asserts the RTS handshake signal line of the specific channel. This function is not available if the channel is configured for hardware handshaking.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;

/*-----
   De-Assert RTS
   -----*/
result = tdrv009RtsClear( hdl );
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_NOTSUP	The channel is in handshake mode, so this function is not allowed.
TDRV009_ERR_ACCESS	This function is not supported by the specific channel.

Other returned error codes are system error conditions.

3.2.10 tdrv009CtsGet

NAME

tdrv009CtsGet – Return status of CTS signal

SYNOPSIS

```
TDRV009_STATUS tdrv009CtsGet
(
    TDRV009_HANDLE          hdl,
    unsigned int             *pCtsState
)
```

DESCRIPTION

This function de-asserts the RTS handshake signal line of the specific channel. This function is not available if the channel is configured for hardware handshaking.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pCtsState

This parameter points to an unsigned int buffer where the status of the CTS signal will be stored. Depending on the state of CTS, either 0 (inactive) or 1 (active) is returned.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;
unsigned int CtsStatus;

/*-----
   Read CTS state
   -----*/
result = tdrv009CtsGet(hdl, &CtsStatus);
if (result == TDRV009_OK)
{
    /* OK */
    printf( "CTS = %d\n", CtsStatus );
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_ACCESS	This function is not supported by the specific channel.

Other returned error codes are system error conditions.

3.2.11 tdrv009DtrSet

NAME

tdrv009DtrSet – Assert DTR Signal

SYNOPSIS

```
TDRV009_STATUS tdrv009DtrSet
(
    TDRV009_HANDLE          hdl
)
```

DESCRIPTION

This function sets the DTR signal line to HIGH. This function is only available for the 4th channel of a TDRV009 module.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;

/*-----
   Set DTR to HIGH (only valid for channel 3)
   -----*/
result = tdrv009DtrSet(hdl);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_ACCESS	This function is not supported by the specific channel.

Other returned error codes are system error conditions.

3.2.12 tdrv009DtrClear

NAME

tdrv009DtrClear – De-Assert DTR Signal

SYNOPSIS

```
TDRV009_STATUS tdrv009DtrClear
(
    TDRV009_HANDLE          hdl
)
```

DESCRIPTION

This function sets the DTR signal line to LOW. This function is only available for the 4th channel of a TDRV009 module.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;

/*-----
   Set DTR to LOW (only valid for channel 3)
   -----*/
result = tdrv009DtrClear(hdl);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_ACCESS	This function is not supported by the specific channel.

Other returned error codes are system error conditions.

3.2.13 tdrv009DsrGet

NAME

tdrv009DsrGet – Return status of DSR signal

SYNOPSIS

```
TDRV009_STATUS tdrv009DsrGet
(
    TDRV009_HANDLE          hdl,
    unsigned int            *pDsrState
)
```

DESCRIPTION

This function returns the current state of the DSR signal line of the specific channel. This function is only available for the 4th channel of a TDRV009 module

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pDsrState

This parameter points to an unsigned int buffer where the status of the DSR signal will be stored. Depending on the state of DSR, either 0 (inactive) or 1 (active) is returned.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;
unsigned int DsrStatus;

/*-----
   Read DSR state
   -----*/
result = tdrv009DsrGet(hdl, &DsrStatus);
if (result == TDRV009_OK)
{
    /* OK */
    printf( "DSR = %d\n", DsrStatus);
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_ACCESS	This function is not supported by the specific channel.

Other returned error codes are system error conditions.

3.2.14 tdrv009SetExternalXtal

NAME

tdrv009SetExternalXtal – Configure externally supplied oscillator frequency

SYNOPSIS

```
TDRV009_STATUS tdrv009SetExternalXtal
(
    TDRV009_HANDLE          hdl,
    int                     XtalFrequency
)
```

DESCRIPTION

This function specifies the frequency of an externally provided clock. This frequency is used for baudrate calculation, and describes the input frequency to the Baud Rate Generator (BRG). The external frequency may be supplied either at input line TxC or RxC.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

XtalFrequency

This parameter specifies the clock frequency in Hz.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE  hdl;
TDRV009_STATUS  result;

/*-----
   Specify 1MHz as external clock frequency
   -----*/
result = tdrv009SetExternalXtal(hdl, 1000000);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.15 tdrv009SetReadTimeout

NAME

tdrv009SetReadTimeout – Specify a timeout for read operations

SYNOPSIS

```
TDRV009_STATUS tdrv009SetReadTimeout  
(  
    TDRV009_HANDLE          hdl,  
    unsigned int            timeout  
)
```

DESCRIPTION

This function specifies the timeout used for read operations. The parameter *timeout* passes an unsigned int value containing the new timeout value (in jiffies, i.e. system-ticks).

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

timeout

This parameter specifies the timeout value in jiffies (i.e. system-ticks).

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;

/*-----
   specify the read-timeout (1000 clock ticks)
   -----*/
result = tdrv009SetReadTimeout(hdl, 1000);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.16 tdrv009GetTxCountError

NAME

tdrv009GetTxCountError – Read the transmit error counter

SYNOPSIS

```
TDRV009_STATUS tdrv009GetTxCountError  
(  
    TDRV009_HANDLE          hdl,  
    unsigned int            *pCount  
)
```

DESCRIPTION

This function returns the global transmit error counter for the corresponding channel. The transmit error counter is reset after a call to this function.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pCount

This parameter specifies a pointer to an unsigned int value where the counter value will be stored.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;
unsigned int   ErrorCount;

/*-----
   Read Transmit Error Counter
   -----*/
result = tdrv009GetTxCountError(hdl, &ErrorCount);
if (result == TDRV009_OK)
{
    /* OK */
    printf("ErrorCount = %d\n", ErrorCount );
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.17 tdrv009GetTxCountOk

NAME

tdrv009GetTxCountOk – Read the transmit success counter

SYNOPSIS

```
TDRV009_STATUS tdrv009GetTxCountOk
(
    TDRV009_HANDLE          hdl,
    unsigned int            *pCount
)
```

DESCRIPTION

This function returns the global transmit success counter for the corresponding channel. The transmit success counter is reset after a call to this function.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pCount

This parameter specifies a pointer to an unsigned int value where the counter value will be stored.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE hdl;
TDRV009_STATUS result;
unsigned int OkCount;

/*-----
   Read Transmit Success Counter
   -----*/
result = tdrv009GetTxCountOk(hdl, &OkCount);
if (result == TDRV009_OK)
{
    /* OK */
    printf("OkCount = %d\n", OkCount );
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.

Other returned error codes are system error conditions.

3.2.18 tdrv009SccRegisterRead

NAME

tdrv009SccRegisterRead – Read from Controller’s SCC Register Space

SYNOPSIS

```
TDRV009_STATUS tdrv009SccRegisterRead
(
    TDRV009_HANDLE      hdl,
    TDRV009_ADDR_STRUCT *pRegisterBuffer
)
```

DESCRIPTION

This function reads one 32bit word from the communication controller’s channel-specific SCC register space.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pRegisterBuffer

This parameter is a pointer to a *TDRV009_ADDR_STRUCT* structure.

```
typedef struct
{
    unsigned int    Offset;
    unsigned int    Value;
} TDRV009_ADDR_STRUCT;
```

Offset

This parameter specifies a byte offset into the communication controller’s channel-specific SCC register space, relative to the start of the channel’s SCC register area. Please refer to the hardware user manual for further information.

Value

This parameter returns the 32bit word from the communication controller’s channel-specific SCC register space.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE          hdl;
TDRV009_STATUS          result;
TDRV009_ADDR_STRUCT    AddrBuf;

/*-----
   Read a 32bit value (Status Register)
   -----*/
AddrBuf.Offset = 0x0004;
result = tdrv009SccRegisterRead ( hdl, &AddrBuf );
if (result == TDRV009_OK)
{
    printf( "Value = 0x%X\n", AddrBuf.Value );
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. The specified offset is invalid.

Other returned error codes are system error conditions.

3.2.19 tdrv009SccRegisterWrite

NAME

tdrv009SccRegisterWrite – Write to Controller’s SCC Register Space

SYNOPSIS

```
TDRV009_STATUS tdrv009SccRegisterWrite
(
    TDRV009_HANDLE          hdl,
    TDRV009_ADDR_STRUCT    *pRegisterBuffer
)
```

DESCRIPTION

This function writes one 32bit word to the communication controller’s channel-specific SCC register space.

Modifying register contents may result in communication problems, system crash or other unexpected behavior.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pRegisterBuffer

This parameter is a pointer to a *TDRV009_ADDR_STRUCT* structure.

```
typedef struct
{
    unsigned int    Offset;
    unsigned int    Value;
} TDRV009_ADDR_STRUCT;
```

Offset

This parameter specifies a byte offset into the communication controller’s channel-specific SCC register space, relative to the start of the channel’s SCC register area. Please refer to the hardware user manual for further information.

Value

This 32bit word will be written to the communication controller’s channel-specific SCC register space.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
TDRV009_ADDR_STRUCT AddrBuf;

/*-----
   Write a 32bit value (Termination Character Register)
   -----*/
AddrBuf.Offset = 0x0048;
AddrBuf.Value  = (1 << 15) | 0x42;
result = tdrv009SccRegisterWrite ( hdl, &AddrBuf );
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. The specified offset is invalid.

Other returned error codes are system error conditions.

3.2.20 tdrv009GlobalRegisterRead

NAME

tdrv009GlobalRegisterRead – Read from Controller’s Global Register Space

SYNOPSIS

```
TDRV009_STATUS tdrv009GlobalRegisterRead
(
    TDRV009_HANDLE          hdl,
    TDRV009_ADDR_STRUCT    *pRegisterBuffer
)
```

DESCRIPTION

This function reads one 32bit word from the communication controller’s Global Register Space.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pRegisterBuffer

This Parameter is a pointer to a *TDRV009_ADDR_STRUCT* structure.

```
typedef struct
{
    unsigned int    Offset;
    unsigned int    Value;
} TDRV009_ADDR_STRUCT;
```

Offset

This parameter specifies a byte offset into the communication controller’s global register space. Please refer to the hardware user manual for further information.

Value

This parameter returns the 32bit word from the communication global register space.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
TDRV009_ADDR_STRUCT AddrBuf;

/*-----
   Read a 32bit value (Version Register)
   -----*/
AddrBuf.Offset = 0x00F0;
result = tdrv009GlobalRegisterRead ( hdl, &AddrBuf );
if (result == TDRV009_OK)
{
    printf( "Value = 0x%X\n", AddrBuf.Value );
} else {
    /* handle error */
}

```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. The specified offset is invalid.

Other returned error codes are system error conditions.

3.2.21 tdrv009GlobalRegisterWrite

NAME

tdrv009GlobalRegisterWrite – Write to controller’s Global Register Space

SYNOPSIS

```
TDRV009_STATUS tdrv009GlobalRegisterWrite
(
    TDRV009_HANDLE          hdl,
    TDRV009_ADDR_STRUCT    *pRegisterBuffer
)
```

DESCRIPTION

This function writes one 32bit word to the communication controller’s Global Register Space.

Modifying register contents may result in communication problems, system crash or other unexpected behavior.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pRegisterBuffer

This Parameter is a pointer to a *TDRV009_ADDR_STRUCT* structure.

```
typedef struct
{
    unsigned int    Offset;
    unsigned int    Value;
} TDRV009_ADDR_STRUCT;
```

Offset

This parameter specifies a byte offset into the communication controller’s global register space. Please refer to the hardware user manual for further information.

Value

This 32bit word will be written to the communication controller’s global register space.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
TDRV009_ADDR_STRUCT AddrBuf;

/*-----
   Write a 32bit value (FIFO Control Register 4)
   -----*/
AddrBuf.Offset = 0x0034;
AddrBuf.Value  = 0xffffffff;
result = tdrv009GlobalRegisterWrite ( hdl, &AddrBuf );
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. The specified offset is invalid.

Other returned error codes are system error conditions.

3.2.2 tdrv009EepromRead

NAME

tdrv009EepromRead – Read from EEPROM

SYNOPSIS

```
TDRV009_STATUS tdrv009EepromRead
(
    TDRV009_HANDLE          hdl,
    TDRV009_EEPROM_BUFFER *pEepromBuffer
)
```

DESCRIPTION

This function reads one 16bit word from the onboard EEPROM.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pEepromBuffer

This parameter is a pointer to a *TDRV009_EEPROM_BUFFER* structure.

```
typedef struct
{
    unsigned int    Offset;
    unsigned short Value;
} TDRV009_EEPROM_BUFFER;
```

Offset

This parameter specifies a 16bit word offset into the EEPROM.
Following offsets are available:

Offset	Access
00h – 5Fh	R
60h – 7Fh	R / W

Value

This parameter returns the 16bit word from the EEPROM at the given offset.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
TDRV009_EEPROM_BUFFER  EepromBuf;

/*-----
   Read a 16bit value into the EEPROM, offset 0
   -----*/
EepromBuf.Offset = 0;
result = tdrv009EepromRead( hdl, &EepromBuf);
if (result == TDRV009_OK)
{
    printf( "Value = 0x%X\n", EepromBuf.Value );
} else {
    /* handle error */
}
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. The specified offset is invalid.

Other returned error codes are system error conditions.

3.2.23 tdrv009EepromWrite

NAME

tdrv009EepromWrite – Write from EEPROM

SYNOPSIS

```
TDRV009_STATUS tdrv009EepromWrite
(
    TDRV009_HANDLE          hdl,
    TDRV009_EEPROM_BUFFER *pEepromBuffer
)
```

DESCRIPTION

This function writes one 16bit word into the onboard EEPROM. The first part of the EEPROM is reserved for factory usage, write accesses to this area will result in an error.

PARAMETERS

hdl

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pEepromBuffer

This parameter is a pointer to a *TDRV009_EEPROM_BUFFER* structure.

```
typedef struct
{
    unsigned int    Offset;
    unsigned short Value;
} TDRV009_EEPROM_BUFFER;
```

Offset

This parameter specifies a 16bit word offset into the EEPROM. Following offsets are available:

Offset	Access
00h – 5Fh	R
60h – 7Fh	R / W

Value

This parameter specifies the 16bit word to be written into the EEPROM at the given offset.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
TDRV009_EEPROM_BUFFER  EepromBuf;

/*-----
   Write a 16bit value into the EEPROM, offset 60h
   -----*/
EepromBuf.Offset = 0x60;
EepromBuf.Value = 0x1234;
result = tdrv009EepromWrite( hdl, &EepromBuf);
if (result == TDRV009_OK)
{
    /* OK */
} else {
    /* handle error */
}
```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_INVALID_PARAMETER	Invalid parameter specified. The specified offset is invalid.

Other returned error codes are system error conditions.

3.2.24 tdrv009WaitForInterrupt

NAME

tdrv009WaitForInterrupt – Wait for SCC Interrupt Event

SYNOPSIS

```
TDRV009_STATUS tdrv009WaitForInterrupt  
(  
    TDRV009_HANDLE          hdl,  
    TDRV009_WAIT_STRUCT    *pWaitBuffer  
)
```

DESCRIPTION

This function waits until a specified SCC interrupt or the timeout occurs.

PARAMETERS

handle

This value specifies the device handle to the hardware module retrieved by a call to the corresponding open-function.

pWaitBuffer

This parameter is a pointer to a *TDRV009_WAIT_STRUCT* structure.

```
typedef struct  
{  
    unsigned int    Interrupts;  
    int             Timeout;  
} TDRV009_WAIT_STRUCT;
```

Interrupts

This parameter specifies interrupt bits to wait for. If at least one interrupt occurs, the value is returned in this parameter. Please refer to the hardware user manual for further information on the possible SCC interrupt bits.

Timeout

This parameter specifies the time (in system ticks) to wait for an interrupt. If -1 is specified, the function will block indefinitely.

EXAMPLE

```
#include "tdrv009api.h"

TDRV009_HANDLE      hdl;
TDRV009_STATUS      result;
TDRV009_WAIT_STRUCT WaitStruct;

/*-----
   Wait at least 5 seconds (5*HZ) for a
   CTS Staus Change (CSC) interrupt
   -----*/
WaitStruct.Interrupts = (1 << 14);
WaitStruct.Timeout    = 5*HZ;

result = tdrv009WaitForInterrupt(hdl, &WaitStruct);
if (result == TDRV009_OK)
{
    printf( "Occurred Interrupt = 0x%X\n", WaitStruct.Interrupts );
} else {
    /* handle error */
}

```

RETURNS

On success, TDRV009_OK is returned. In the case of an error, the appropriate error code is returned by the function.

ERROR CODES

Error Code	Description
TDRV009_ERR_INVALID_HANDLE	The specified TDRV009_HANDLE is invalid.
TDRV009_ERR_BUSY	Too many concurrent wait jobs pending (max. 10)
TDRV009_ERR_TIMEOUT	Timeout. None of the specified events occurred.

Other returned error codes are system error conditions.