

The Embedded I/O Company



TIP501

Optically Isolated 16 Channel 16 Bit ADC

Version 1.1

User Manual

Issue 1.1.7

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TIP501-10

Optically isolated 16 channel 16 bit ADC input voltage range +/-10V, gain 1, 2, 5, 10

TIP501-11

Optically isolated 16 channel 16 bit ADC input voltage range +/-10V, gain 1, 2, 4, 8

TIP501-20

Optically isolated 16 channel 16 bit ADC input voltage range 0V to +10V, gain 1, 2, 5, 10

TIP501-21

Optically isolated 16 channel 16 bit ADC input voltage range 0V to +10V, gain 1, 2, 4, 8

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Style Conventions

Hexadecimal characters are specified with prefix 0x, i.e. 0x029E (that means hexadecimal value 029E).

For signals on hardware products, an 'Active Low' is represented by the signal name with # following, i.e. IP_RESET#.

Access terms are described as:

W	Write Only
R	Read Only
R/W	Read/Write
R/C	Read/Clear
R/S	Read/Set

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Issue	Description	Date
1.0	First Issue	March 1997
1.1	Formula Correction and General Revision	November 2002
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1.1.6	New Notation for User Manual and Engineering Documentation	January 2009
1.1.7	Added Analog Input Impedance	January 2010

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1 Product Description

The TIP501 is an IndustryPack® compatible module providing 16 single-ended or 8 differential channels of isolated 16 bit A/D conversion.

The data acquisition and conversion time is up to 12µs without channel / gain change and up to 14.5µs with channel / gain change.

The input multiplexer offers analog overvoltage protection of up to 70Vpp.

A programmable gain amplifier supports various input voltage ranges.

The input voltage range depends on the board option and the programmed gain factor.

Board Option	Gain Factors	Input Voltage Range
TIP501-10	1, 2, 5, 10	±10V for gain = 1
TIP501-11	1, 2, 4, 8	±10V for gain = 1
TIP501-20	1, 2, 5, 10	0V to 10V for gain = 1
TIP501-21	1, 2, 4, 8	0V to 10V for gain = 1

Table 1-1 : Board Option Overview

The analog I/O part and the ADC device are isolated from the system logic power supply by optocouplers and a DC/DC converter.

Interrupts are supported indicating available sampling data when conversion is done.

Each TIP501 is factory calibrated. The calibration information is stored in the Identification-PROM unique to each IP.

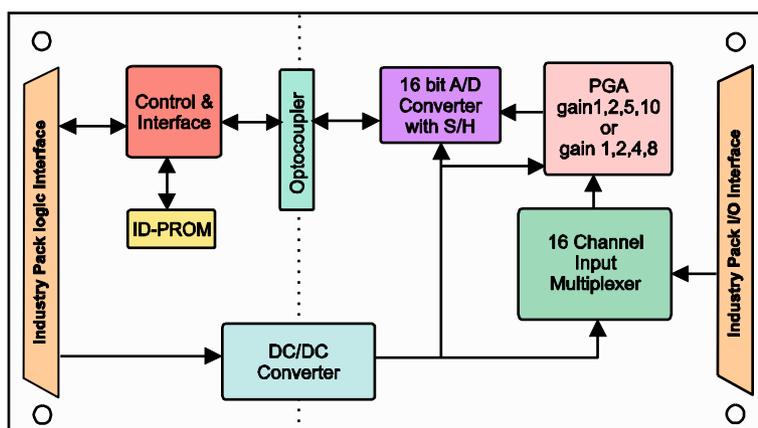


Figure 1-1 : Block Diagram

2 Technical Specification

IP Interface																																		
Interface	Single Size IndustryPack® Logic Interface compliant to ANSI/VITA 4-1995																																	
ID ROM Data	Format I																																	
I/O Space	Used with 0 wait states																																	
Memory Space	not used																																	
Interrupts	INTREQ0# and INTREQ1# used																																	
DMA	Not supported																																	
Clock Rate	8 MHz																																	
Module Type	Type I																																	
On Board Devices																																		
ADC	ADS7809 - 16-Bit ANALOG-TO-DIGITAL CONVERTER																																	
I/O Interface																																		
Interface Connector	50-conductor flat cable																																	
Analog Inputs	16 single-ended channels or 8 differential channels																																	
Input Impedance	Typically $10^{12} \Omega$ (4nA leakage current)																																	
Input Isolation	All channels are galvanically isolated from the IP interface, DC/DC converter on board																																	
Input Gain Amplifier	TIP501-10/-20: Programmable for gain 1, 2, 5, 10 TIP501-11/-21: Programmable for gain 1, 2, 4, 8																																	
Input Voltage Range	<table border="0"> <tr> <td><u>TIP501-10:</u></td> <td><u>TIP501-20:</u></td> <td></td> </tr> <tr> <td>±10V</td> <td>0V to 10V</td> <td>(gain = 1)</td> </tr> <tr> <td>±5V</td> <td>0V to 5V</td> <td>(gain = 2)</td> </tr> <tr> <td>±2V</td> <td>0V to 2V</td> <td>(gain = 5)</td> </tr> <tr> <td>±1V</td> <td>0V to 1V</td> <td>(gain = 10)</td> </tr> <tr> <td colspan="3"> </td> </tr> <tr> <td><u>TIP501-11:</u></td> <td><u>TIP501-21:</u></td> <td></td> </tr> <tr> <td>±10V</td> <td>0V to 10V</td> <td>(gain = 1)</td> </tr> <tr> <td>±5V</td> <td>0V to 5V</td> <td>(gain = 2)</td> </tr> <tr> <td>±2.5V</td> <td>0V to 2.5V</td> <td>(gain = 4)</td> </tr> <tr> <td>±1.25V</td> <td>0V to 1.25V</td> <td>(gain = 8)</td> </tr> </table>	<u>TIP501-10:</u>	<u>TIP501-20:</u>		±10V	0V to 10V	(gain = 1)	±5V	0V to 5V	(gain = 2)	±2V	0V to 2V	(gain = 5)	±1V	0V to 1V	(gain = 10)				<u>TIP501-11:</u>	<u>TIP501-21:</u>		±10V	0V to 10V	(gain = 1)	±5V	0V to 5V	(gain = 2)	±2.5V	0V to 2.5V	(gain = 4)	±1.25V	0V to 1.25V	(gain = 8)
<u>TIP501-10:</u>	<u>TIP501-20:</u>																																	
±10V	0V to 10V	(gain = 1)																																
±5V	0V to 5V	(gain = 2)																																
±2V	0V to 2V	(gain = 5)																																
±1V	0V to 1V	(gain = 10)																																
<u>TIP501-11:</u>	<u>TIP501-21:</u>																																	
±10V	0V to 10V	(gain = 1)																																
±5V	0V to 5V	(gain = 2)																																
±2.5V	0V to 2.5V	(gain = 4)																																
±1.25V	0V to 1.25V	(gain = 8)																																
Input Overvoltage	Protection up to 70Vpp																																	
Input ADC	16 bit ADC Data acquisition and conversion time up to 12µs without channel / gain change and up to 14.5µs with channel / gain change (mode-dependent)																																	
Calibration Data	Stored in ID PROM for gain and offset correction																																	
Accuracy	For all TIP501 modules: ± 4LSB after calibration																																	
Linearity	For all TIP501 modules: ± 4LSB																																	
No Missing Code	Minimum 15 bit																																	
Power Requirements	380mA typical @ +5V DC																																	

Physical Data		
Temperature Range	Operating	-40 °C to +85 °C
	Storage	-45°C to +125°C
MTBF	637000 h MTBF values shown are based on calculation according to MIL-HDBK-217F and MIL-HDBK-217F Notice 2; Environment: G _B 20°C. The MTBF calculation is based on component FIT rates provided by the component suppliers. If FIT rates are not available, MIL-HDBK-217F and MIL-HDBK-217F Notice 2 formulas are used for FIT rate calculation.	
Humidity	5 – 95 % non-condensing	
Weight	31 g	

Table 2-1 : Technical Specification

3 Functional Description

3.1 Analog Input

The TIP501 provides 16 single-ended or 8 differential multiplexed analog inputs. The desired input channel and mode (single-ended or differential) is selected by programming the input multiplexer.

A programmable gain amplifier allows a direct connection for a wide range of sensors and instrumentation.

Board Option	Gain Factors	Input Voltage Range
TIP501-10	1, 2, 5, 10	±10V for gain = 1
TIP501-11	1, 2, 4, 8	±10V for gain = 1
TIP501-20	1, 2, 5, 10	0V to 10V for gain = 1
TIP501-21	1, 2, 4, 8	0V to 10V for gain = 1

Table 3-1 : Board Option Overview

The ADC device is a 16 bit ADS7809 with a maximum sample and conversion time of 10µs.

Since the TIP501 is a multiplexed analog input system, a settling time is required to pass after changing the input channel and / or gain. The TIP501 provides a status bit for polling the settling time status. An automatic settling time control mode is also provided. In this mode, data conversion is automatically started after the settling time has expired.

The absolute accuracy of the module can be increased by performing a data correction in software, using the factory calibration factors stored in the on board ID PROM.

3.2 Data Correction

There are two errors which affect the DC accuracy of the ADC. The first is the zero error (offset). This is the data value, when converting with the input connected with its own ground in single-ended mode, or with shorted inputs in differential mode. This error is corrected by subtracting the known error from all readings.

The second error is the gain error. Gain error is the difference between the ideal gain and the actual gain of the programmable gain amplifier and the ADC. It is corrected by multiplying the data value by a correction factor.

The data correction values are obtained during factory calibration and are stored in the modules individual version of the ID PROM. The ADC has a pair of offset and gain correction values for each of the programmable gains.

The correction values are stored in the ID PROM as two's complement 16 bit values in the range -32768 to 32767. For higher accuracy they are scaled to ¼ LSB.

3.2.1 ADC Correction Formula

The basic formula for correcting any ADC reading for the TIP501-10/-11 (bipolar input voltage range) is:

$$Value = Reading * (1 - Gain_{corr} / 131072) - Offset_{corr} / 4$$

The basic formula for correcting any ADC reading for the TIP501-20/-21 (unipolar input voltage range) is:

$$Value = Reading * (1 - Gain_{corr} / 262144) - Offset_{corr} / 4$$

Value is the corrected result. Reading is the data read from the ADC data register.

Gain_{corr} and Offset_{corr} are the correction factors from the ID PROM. Gain_{corr} and Offset_{corr} correction factors are stored for each gain factor.

Floating point arithmetic or scaled integer arithmetic is necessary to avoid rounding errors while computing above formula.

4 ID PROM Content

Address	Function	Contents
0x01	ASCII 'I'	0x49
0x03	ASCII 'P'	0x50
0x05	ASCII 'A'	0x41
0x07	ASCII 'C'	0x43
0x09	Manufacturer ID	0xB3
0x0B	Model Number	0x22
0x0D	Revision	0x10
0x0F	Reserved	0x00
0x11	Driver-ID low - byte	0x00
0x13	Driver-ID high - byte	0x00
0x15	Number of bytes used	0x1D
0x17	CRC	Variable
0x19	Board Option	TIP501-10 : 0x0A TIP501-11 : 0x0B TIP501-20 : 0x14 TIP501-21 : 0x15
0x1B	Offset Error for gain = 1 low byte	Board dependent
0x1D	Offset Error for gain = 1 high byte	Board dependent
0x1F	Offset Error for gain = 2 low byte	Board dependent
0x21	Offset Error for gain = 2 high byte	Board dependent
0x23	Offset Error for gain =4/5 low byte	Board dependent
0x25	Offset Error for gain =4/5 high byte	Board dependent
0x27	Offset Error for gain = 8/10 low byte	Board dependent
0x29	Offset Error for gain = 8/10 high byte	Board dependent
0x2B	Gain Error for gain = 1 low byte	Board dependent
0x2D	Gain Error for gain = 1 high byte	Board dependent
0x2F	Gain Error for gain = 2 low byte	Board dependent
0x31	Gain Error for gain = 2 high byte	Board dependent
0x33	Gain Error for gain = 4/5 low byte	Board dependent
0x35	Gain Error for gain = 4/5 high byte	Board dependent
0x37	Gain Error for gain = 8/10 low byte	Board dependent
0x39	Gain Error for gain = 8/10 high byte	Board dependent
0x3B ... 0x3F	Not used	

Table 4-1 : ID PROM Content TIP501

5 IP Addressing

The TIP501 is controlled by a set of registers, which are directly accessible in the I/O address space of the IP module.

Address	Symbol	Description	Size (Bit)	Access
0x00	CONTREG	ADC Control Register	16	R/W
0x02	DATAREG	ADC Data Register	16	R/W
0x05	STATREG	ADC Status Register	8	R
0x07	CONVERT	ADC Convert Start Register	8	W
0x09	INTVEC	Interrupt Vector Register	8	R/W
0x0B	IDWRENA	ID PROM write enable	8	W

Table 5-1 : Register Set

IDWRENA is for factory use only. Do not write to this register.

5.1 ADC Register Set

The ADC of the TIP501 is controlled by a set of 4 registers. All registers are cleared by IP_RESET#.

- ADC Control Register
- ADC Data Register
- ADC Status Register
- ADC Convert Start Register

5.1.1 ADC Control Register (Address 0x00)

The ADC Control Register CONTREG is used to select the input channel, gain and mode for the next data conversion.

Bit	Symbol	Description	Access	Reset Value
15:10		Unused bits. Read access undefined. Write access don't care.	R/W	0
9	INTENA	Interrupt Enable 0 = Interrupts disabled 1 = Interrupts enabled IP INTREQ1# is generated when the settling time is done. IP INTREQ0# is generated when a data conversion is done. In Automatic Settling Time mode, only IP INTREQ0 is generated.	R/W	0

Bit	Symbol	Description	Access	Reset Value										
8	PIPL	<p>Pipeline Mode Control</p> <p>0 = No Pipeline Mode</p> <p>1 = Pipeline Mode</p> <p>In pipeline mode, the result from the conversion (N-1) is shifted into the ADC DATAREG during the conversion N.</p>	R/W	0										
7	ASTCE	<p>Automatic Settling Time Mode Control</p> <p>0 = Normal Settling Time Mode</p> <p>In this mode first the input channel and gain is selected by writing the ADC CONTREG register.</p> <p>The data conversion is started by writing to the ADC CONVERT register.</p> <p>The Settle Busy bit in the ADC STATREG register must be '0' for every write to the ADC CONVERT register.</p> <p>The ADC Busy bit in the ADC STATREG register must be '0' for reading the ADC DATAREG register.</p> <p>1 = Automatic Settling Time Mode</p> <p>In this mode the data conversion is started by the write to the ADC CONTREG register where this bit is set. The data conversion is delayed by hardware control until the settling time has expired.</p> <p>The ADC Busy bit in the ADC STATREG register must be '0' for reading the ADC DATAREG register.</p> <p>The settling time for all TIP501 modules is appr. 10µs for all gains.</p>	R/W	0										
6	GAIN1	<p>Gain Selection (input voltage amplifier)</p> <table border="0" style="width: 100%;"> <tr> <td style="text-align: center;"><u>TIP501-10/-20 :</u></td> <td style="text-align: center;"><u>TIP501-11/-21 :</u></td> </tr> <tr> <td style="text-align: center;">00 = G1</td> <td style="text-align: center;">00 = G1</td> </tr> <tr> <td style="text-align: center;">01 = G2</td> <td style="text-align: center;">01 = G2</td> </tr> <tr> <td style="text-align: center;">10 = G5</td> <td style="text-align: center;">10 = G4</td> </tr> <tr> <td style="text-align: center;">11 = G10</td> <td style="text-align: center;">11 = G8</td> </tr> </table>	<u>TIP501-10/-20 :</u>	<u>TIP501-11/-21 :</u>	00 = G1	00 = G1	01 = G2	01 = G2	10 = G5	10 = G4	11 = G10	11 = G8	R/W	0
<u>TIP501-10/-20 :</u>	<u>TIP501-11/-21 :</u>													
00 = G1	00 = G1													
01 = G2	01 = G2													
10 = G5	10 = G4													
11 = G10	11 = G8													
5	GAIN0													
4	DIF	<p>Differential Mode Selection</p> <p>0 = Single-ended Mode, 16 single-ended channels (1-16) are available</p> <p>1 = Differential Mode, 8 differential channels (1-8) are available. Channels 9-16 are used as 2 input for channels 1-8.</p>	R/W	0										
3	CS3	<p>Channel Selection (input channel selection for data conversion)</p> <table border="0" style="width: 100%;"> <tr> <td style="text-align: center;"><u>Single-ended :</u></td> <td style="text-align: center;"><u>Differential :</u></td> </tr> <tr> <td style="text-align: center;">0000 = CH1</td> <td style="text-align: center;">0000 = CH1</td> </tr> <tr> <td style="text-align: center;">..</td> <td style="text-align: center;">..</td> </tr> <tr> <td style="text-align: center;">..</td> <td style="text-align: center;">..</td> </tr> <tr> <td style="text-align: center;">1111 = CH16</td> <td style="text-align: center;">0111 = CH8</td> </tr> </table>	<u>Single-ended :</u>	<u>Differential :</u>	0000 = CH1	0000 = CH1	1111 = CH16	0111 = CH8	R/W	0
<u>Single-ended :</u>	<u>Differential :</u>													
0000 = CH1	0000 = CH1													
..	..													
..	..													
1111 = CH16	0111 = CH8													
2	CS2													
1	CS1													
0	CS0													

Table 5-2 : CONTREG - ADC Control Register (Address 0x00)

5.1.2 ADC Data Register (Address 0x02)

The ADC Data Register DATAREG contains the converted data value. The 16 bit ADC value allows direct processing of the data as a 16 bit two's complement integer value for the TIP501-10/11 and 16 bit straight binary for TIP501-20/21.

Description	ADC Data Value	
	Binary two's complement TIP501-10/-11	Straight binary TIP501 -20/-21
+ Full Scale (FS -1LSB)	0x7FFF	0xFFFF
Midscale	0x0000	0x8000
1 LSB Below Midscale	0xFFFF	0x7FFF
- Full Scale	0x8000	0x0000

Table 5-3 : ADC Data Coding

The content of ADC DATAREG is only valid when the ADC Busy Flag is read as '0'.

5.1.3 ADC Status Register (Address 0x05)

Bit 0 and bit 1 of the ADC Status Register STATREG reflect the status for an A/D conversion.

Bit	Symbol	Description	Access	Reset Value
7:2		Undefined bits	R	undefined
1	ADC Busy	ADC Busy Indicates if an actual data conversion is still in progress In Automatic Settling Time mode, the ADC Busy bit is '1' during the settling time and the conversion time. The ADC Busy bit must be read as '0' before the data is read from the ADC DATAREG register.	R	0
0	Settle Busy	Settling Time Busy Indicates if the settling time count is still in progress In Normal Settling Time mode, after writing to the ADC CONTREG register, the Settle Busy bit must be read as '0' before a conversion is started by writing to the ADC CONVERT register.	R	0

Table 5-4 : STATREG - ADC Status Register (Address 0x05)

5.1.4 ADC Convert Start Register (Address 0x07)

If the TIP501 is configured for “Normal Settling Time mode”, writing any value into the ADC Convert Register CONVERT starts a data conversion immediately.

In “Normal Settling Time mode”, it is in the responsibility of the user to observe the Settle Busy flag and the ADC Busy flag in the ADC STATREG register. Writes to the ADC CONVERT register during ADC Busy = '1' are ignored.

5.1.5 Interrupt Vector Register (Address 0x09)

There are two possible interrupt sources:

A "Settling Time Done" event, and an "ADC Data Ready" event.

The Interrupt Vector Register is shared between both interrupt sources, but the “Settling Time Ready” event and the “ADC Data Ready” event will create an individual interrupt. An IP Interrupt Acknowledge cycle acknowledges and clears the interrupt.

Bit	Symbol	Description	Access	Reset Value
7:1		Interrupt vector loaded by software	R/W	0x00
0		Read as '1' for an interrupt from a settling time ready event (Normal Settling Time Mode only). Read as '0' for an interrupt from an “ADC Data Ready” event. For example: If the vector register is loaded with 0x60, a “Settling Time Ready” event will create an interrupt vector '0x61' and a “ADC Data Ready” event will create an interrupt vector '0x60'. In IP I/O space bit 0 of the INTVEC is always read as '0'.	R	0

Table 5-5 : INTVEC – Interrupt Vector Register (Address 0x09)

The "Settling Time Ready" interrupt is generated on the falling edge of the Settle Busy status flag and uses IP INTREQ1#. It is generated in "Normal Settling Time Mode" only.

The "ADC Data Ready" interrupt is generated on the falling edge of the ADC Busy status flag and uses IP INTREQ0#.

6 Operating Modes

The TIP501 supports four operating modes, selected by bit 7 (Normal / Automatic Settling Time Mode) and bit 8 (No Pipeline Mode / Pipeline Mode) of the ADC CONTREG register.

6.1 Mode Overview

- Normal Mode without Data Pipeline
- Automatic Mode without Data Pipeline
- Normal Mode with Data Pipeline
- Automatic Mode with Data Pipeline

	CONTREG Bit 7 = 0 Normal Mode	CONTREG Bit 7 = 1 Automatic Mode
CONTREG Bit 8 = 0 Data Pipeline OFF	A write access to the ADC CONVERT register starts conversion N and shifts the result of conversion N into the ADC DATAREG register	After the settling time has expired conversion N is started and the result of conversion N is shifted into the ADC DATAREG register
CONTREG Bit 8 = 1 Data Pipeline ON	A write access to the ADC CONVERT register starts conversion N and shifts the result of conversion N-1 into the ADC DATAREG register	After the settling time has expired conversion N is started and the result of conversion N-1 is shifted into the ADC DATAREG register

Table 6-1 : Operating Modes

In "Normal Mode" the Settle Busy flag in the ADC STATREG register must be read as '0' before a conversion is started.

6.2 Normal Mode

Any write access to the ADC CONTREG register where bit 7 is set to '0' selects the "Normal Mode" with the selected input channel, input channel mode and gain.

As long as the analog input path settling time has not expired, the Settle Busy flag in the ADC STATREG register is read as '1'. After the settling time has expired a conversion can be started by writing to the ADC CONVERT register.

The conversion data is available in the ADC DATAREG register, when the ADC Busy flag in the ADC STATREG is read as '0'.

It is also possible, to select a next channel and / or gain by writing to the ADC CONTREG register, immediately after the actual conversion has been started by writing to the ADC CONVERT register. In this mode the settling time for the next channel and the conversion time of the actual channel proceed simultaneously. As long as the ADC Busy flag in the ADC STATREG register is read as '1' the actual conversion is still in progress. Reading the ADC Busy flag as '0' indicates that the conversion result is available in the ADC DATAREG register.

If interrupts are enabled, two interrupts will be generated: the first interrupt when the settling time is done after writing to the ADC CONTREG register, the second interrupt when the data conversion is done after writing to the ADC CONVERT register.

6.2.1 State Diagram "Normal Mode"

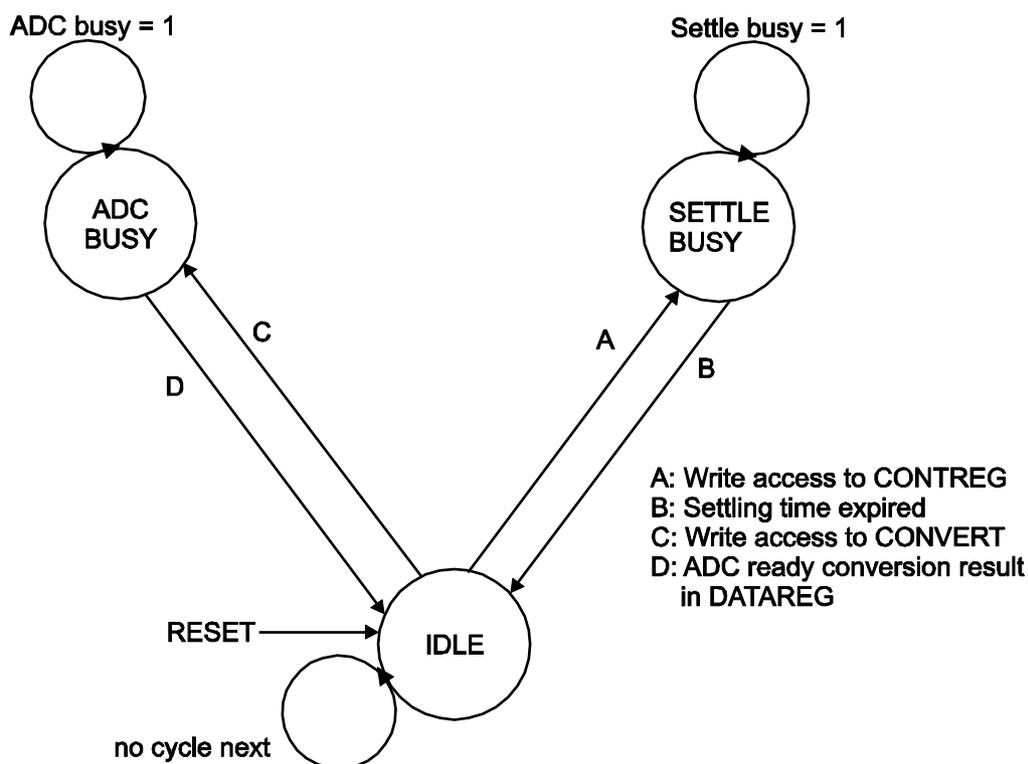


Figure 6-1 : State Diagram "Normal Mode"

6.2.2 “Normal Mode without Data Pipeline”

If “Normal Mode without Data Pipeline” is selected, the result of the actual conversion is shifted into the ADC DATAREG register. In this mode it is possible that the settling time and conversion time proceed simultaneously. The total acquisition and conversion time in this mode is 22 μ s.

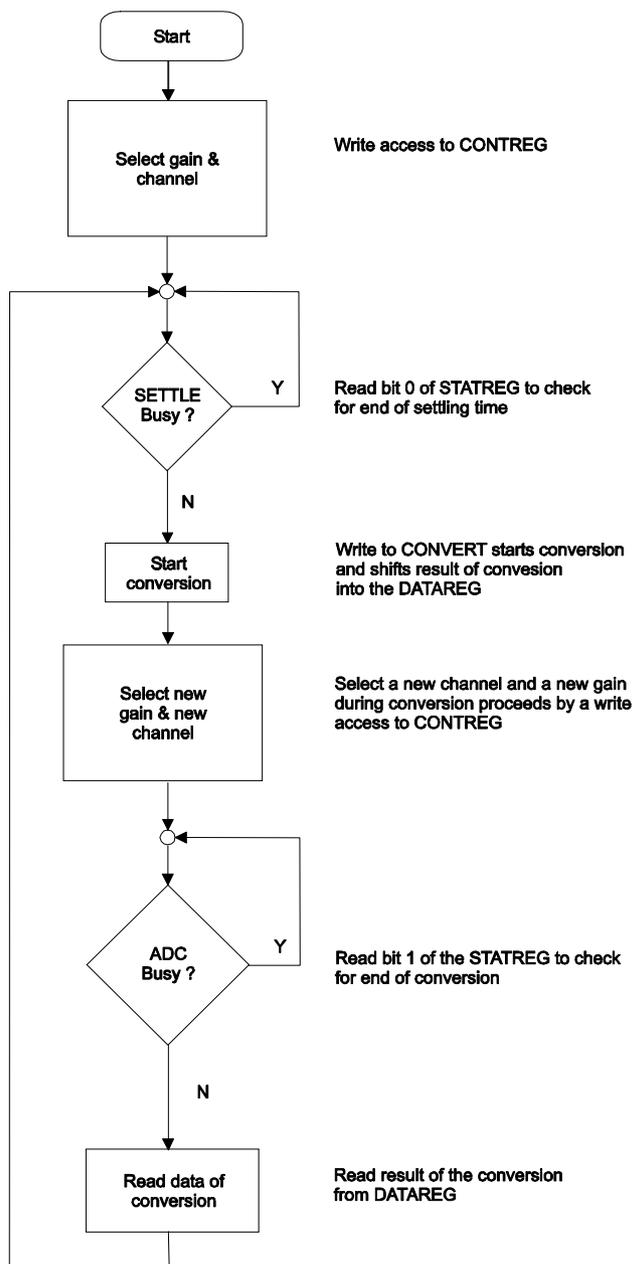


Figure 6-2 : Flowchart “Normal Mode without Data Pipeline”

For conversions without channel and gain change, it is not necessary to observe the Settle Busy flag in the ADC STATREG register.

6.2.3 “Normal Mode with Data Pipeline”

If “Normal Mode with Data Pipeline” is selected, during conversion N the result of conversion N-1 is shifted into the ADC DATAREG register. In this mode it is possible that the settling time and conversion time proceed simultaneously. The total acquisition and conversion time in this mode is 12 μ s with no change of channel / gain and 14.5 μ s with change of channel / gain.

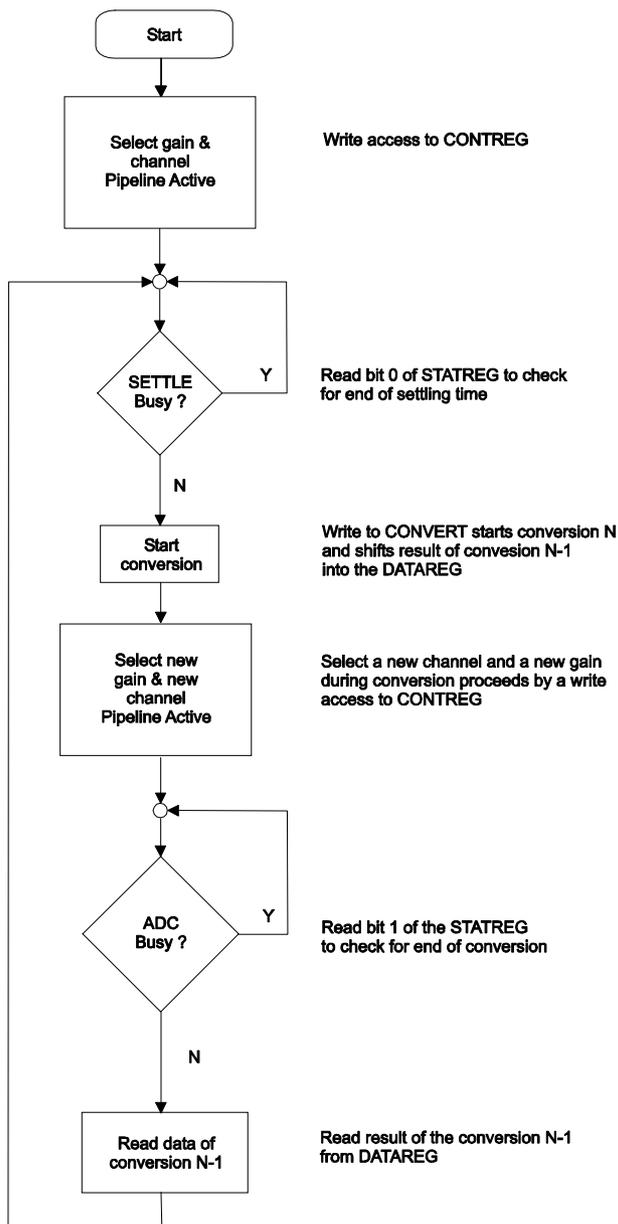


Figure 6-3 : Flowchart “Normal Mode with Data Pipeline”

For conversions without channel and gain change, it is not necessary to observe the Settle Busy flag in the ADC STATREG register.

6.3 Automatic Mode

Any write access to the ADC CONTREG register where bit 7 is set to '1' selects the "Automatic Mode" with the selected input channel, input channel mode and gain.

The data conversion is started automatically by hardware when the settling time expires.

The conversion data is available in the ADC DATAREG register, when the ADC Busy flag in the ADC STATREG is read as '0'.

If interrupts are enabled, an interrupt is generated when the data conversion is done.

6.3.1 State Diagram "Automatic Mode"

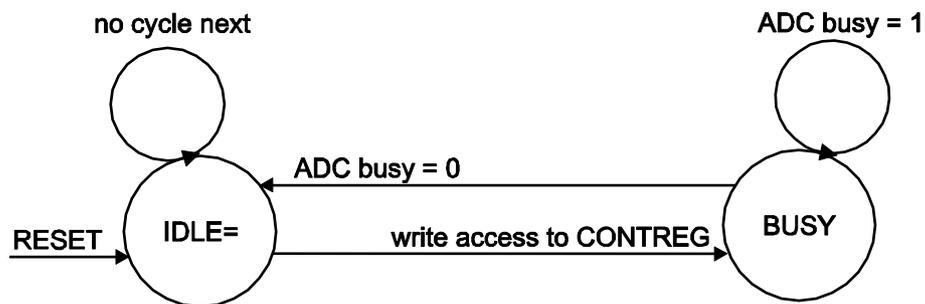


Figure 6-4 : State Diagram "Automatic Mode"

In "Automatic Mode" the ADC busy flag is active during the whole cycle of channel/gain select, settling time and data conversion. When the ADC busy clears to '0' the conversion result is accessible in the ADC DATAREG register and an interrupt will be generated if interrupts are enabled.

6.3.2 “Automatic Mode without Data Pipeline”

If “Automatic Mode without Data Pipeline” is selected the result of the actual conversion is shifted into the ADC Data Register DATAREG. The acquisition and conversion time in this mode is 32µs.

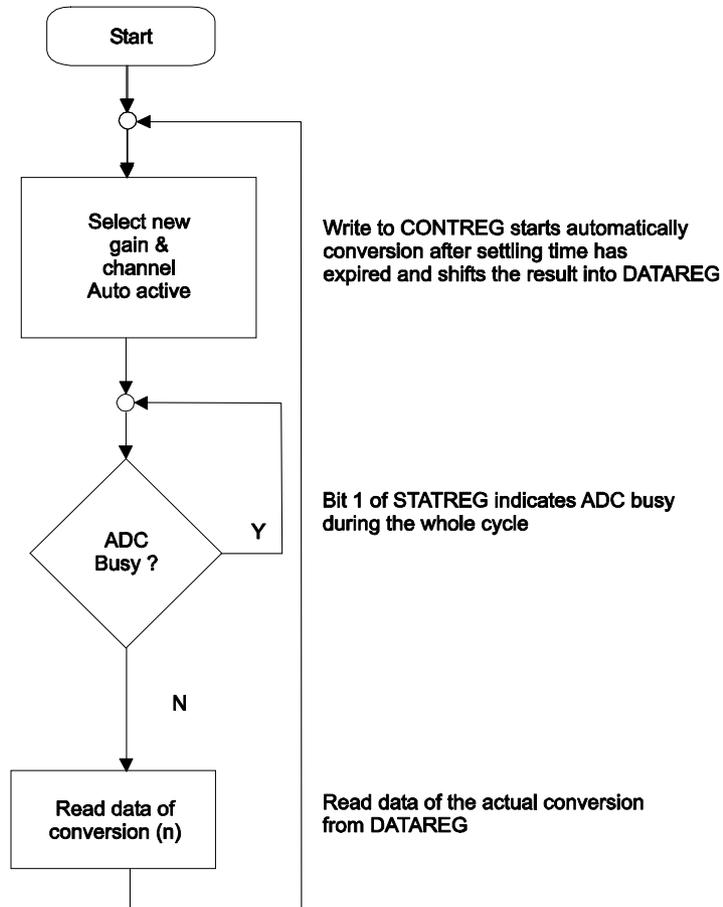


Figure 6-5 : Flowchart “Automatic Mode without Data Pipeline”

6.3.3 “Automatic Mode with Data Pipeline”

If “Automatic Mode with Data Pipeline” is selected, during conversion N, the result of conversion N-1 is shifted into the ADC Data Register DATAREG. The acquisition and conversion time in this mode is 20µs.

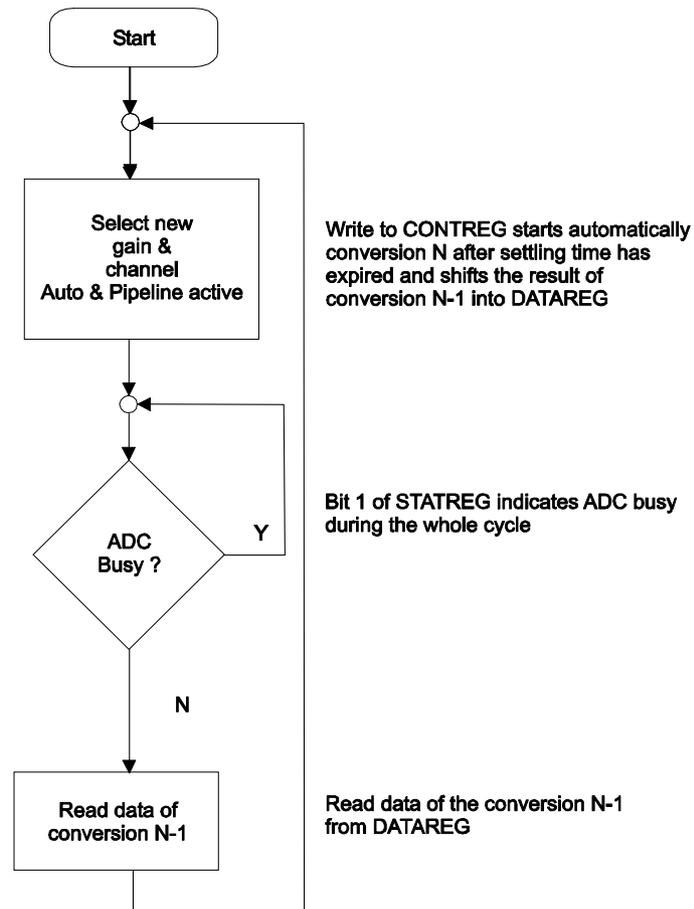


Figure 6-6 : Flowchart “Automatic Mode with Data Pipeline”

7 Pin Assignment – I/O Connector

7.1 Analog Input Connections

Pin	Single-ended Mode	Differential Mode
01	ADC Input 1	ADC Input 1+
02	ADC Input 9	ADC Input 1-
03	AGND	AGND
04	ADC Input 10	ADC Input 2-
05	ADC Input 2	ADC Input 2+
06	AGND	AGND
07	ADC Input 3	ADC Input 3+
08	ADC Input 11	ADC Input 3-
09	AGND	AGND
10	ADC Input 12	ADC Input 4-
11	ADC Input 4	ADC Input 4+
12	AGND	AGND
13	ADC Input 5	ADC Input 5+
14	ADC Input 13	ADC Input 5-
15	AGND	AGND
16	ADC Input 14	ADC Input 6-
17	ADC Input 6	ADC Input 6+
18	AGND	AGND
19	ADC Input 7	ADC Input 7+
20	ADC Input 15	ADC Input 7-
21	AGND	AGND
22	ADC Input 16	ADC Input 8-
23	ADC Input 8	ADC Input 8+
24	AGND	AGND

Table 7-1 : Analog Input Connections

7.2 Power Input Connections

Pin	Signal
44	AGND
45	-15V
46	AGND
47	+15V
48	AGND
49	+5V
50	AGND

Table 7-2 : Power Input Connections

The power input connections are reserved for special versions of the TIP501 without an on board DC/DC converter.

On the standard TIP501 board options (-10, -11, -20, -21) I/O pins 45, 47 and 49 are not connected, I/O pins 44, 46, 48 and 50 are not connected to any on-board signal but are connected to each other.

7.3 IP Connector Orientation

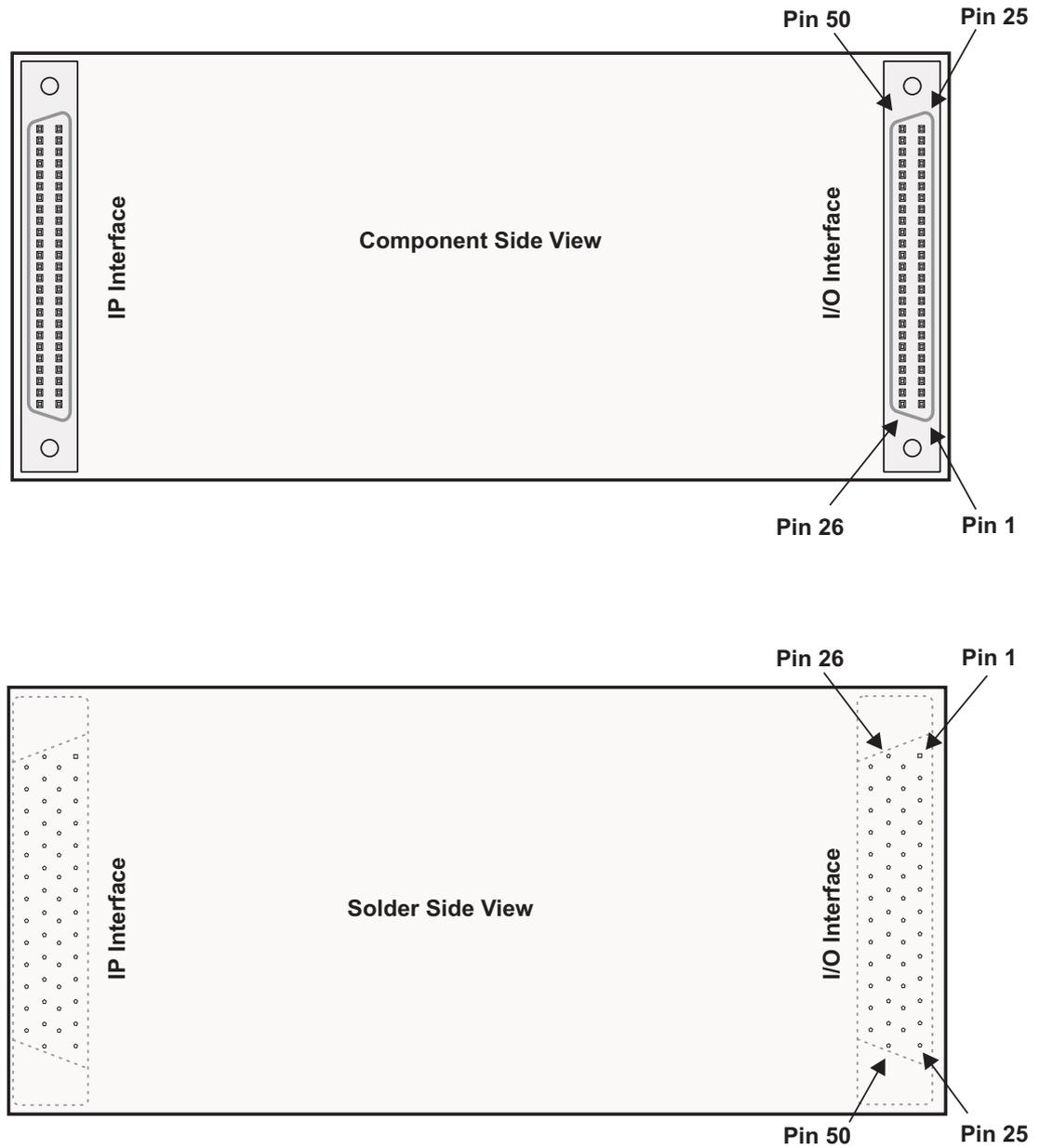


Figure 7-1 : IP Connector Orientation

8 Programming Notes

After power up the on board ADC device is in a random state and requires two dummy conversions before operating correctly. This is based on the chip design of the ADC device.

Software should ignore the data of the first two ADC conversions after power-up.

The software drivers from TEWS TECHNOLOGIES already include these two dummy conversions.

9 Installation Notes

Make sure that all unused analog input pins are tied to the AGND signal level (or any other valid signal level within the analog input voltage range). This is required even if the unused channels are turned off by software.

If unused analog inputs are left floating, they could badly degrade the performance of the active channels.