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TPMC500-SW-95

QNX6 - Neutrino Device Driver

Optically Isolated 32 Channel 12 Bit ADC PMC

Version 1.0.x

User Manual

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TPMC500-SW-95

QNX6 - Neutrino Device Driver

Optically Isolated 32 Channel 16 Bit ADC PMC

Supported Modules:
TPMC500

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Table of Contents

1 Introduction

The TPMC500-SW-95 QNX-Neutrino device driver allows the operation of the TPMC500 product family on QNX-Neutrino operating systems.

The TPMC500 device driver is basically implemented as a user installable Resource Manager. The standard file (I/O) functions (open, close and devctl) provide the basic interface for opening and closing a file descriptor and for performing device I/O and control operations.

The TPMC500-SW-95 device driver supports the following features:

- configure attached module-type
- reading an analog input value (single channel)
- configuring, starting, stopping and using sequencer mode

The TPMC500-SW-95 device driver supports the modules listed below:

TPMC500	Optically Isolated 32 Channel 16 Bit ADC	(PMC)

To get more information about the features and use of TPMC500 devices it is recommended to read the manuals listed below.

TPMC500 User manual
TPMC500 Engineering Manual

2 Installation

Following files are located in the directory TPMC500-SW-95 on the distribution media:

TPMC500-SW-95-SRC.tar.gz	GZIP compressed archive with driver source code
TPMC500-SW-95-1.0.0.pdf	This manual in PDF format
ChangeLog.txt	Release history
Release.txt	Information about the Device Driver Release

The GZIP compressed archive TPMC500-SW-95-SRC.tar.gz contains the following files and directories:

Directory path 'tpmc500':

/driver/tpmc500.c	Driver source code
/driver/tpmc500.h	Definitions and data structures for driver and application
/driver/tpmc500def.h	Device driver include
/driver/node.c	Queue management source code
/driver/node.h	Queue management definitions
/example/tpmc500exa.c	Example application

For installation copy the tar-archive into the /usr/src directory and unpack it (e.g. `tar –xzvf TPMC500-SW-95-SRC.tar.gz`). After that the necessary directory structure for the automatic build and the source files are available underneath the new directory called *tpmc500*.

It is absolutely important to extract the TPMC500 archive in the /usr/src directory. Otherwise the automatic build with make will fail.

2.1 Build the Device Driver

Change to the /usr/src/tpmc500/driver directory

Execute the Makefile:

```
# make install
```

After successful completion the driver binary (tpmc500) will be installed in the /bin directory.

2.2 Build the Example Application

Change to the /usr/src/tpmc500/example directory

Execute the Makefile:

```
# make install
```

After successful completion the example binary (*tpmc500exa*) will be installed in the /bin directory.

2.3 Start the Driver Process

To start the TPMC500 device driver, you have to enter the process name with optional parameter from the command shell or in the startup script.

Possible parameters are:

-v

For debugging purposes you can start the TPMC500 Resource Manager with the –v option. The Resource Manager will print versatile information about TPMC500 configuration and command execution on the terminal window.

Example:

The following startup call will start the TPMC500 device driver in verbose mode:

```
# tpmc500 –v &
```

After the TPMC500 Resource Manager is started, it creates and registers a device for each found supported hardware module. The devices are named `/dev/tpmc500_`**x**, where **x** is the index of the found TPMC500.

```
/dev/tpmc500_0
/dev/tpmc500_1
...
/dev/tpmc500_x
```

This pathname must be used in the application program to open a path to the desired TPMC500.

```
fd = open(“/dev/tpmc500_0”, O_RDWR);
```

3 Device Input/Output Functions

This chapter describes the interface to the device driver I/O system.

3.1 open

NAME

open - open a file descriptor

SYNOPSIS

#include <sys/types.h>
#include <sys/stat.h>
#include <fcntl.h>

int open (const char *pathname, int flags)

DESCRIPTION

The *open* function creates and returns a new file descriptor for the TPMC500 named by pathname. The flags argument controls how the file is to be opened (must be O_RDWR for TPMC500 devices).

EXAMPLE

```
int fd;

fd = open(“/dev/tpmc500_0”, O_RDWR);
if (fd == -1)
{
     /* handle error */
}
```

RETURNS

The normal return value from open is a non-negative integer file descriptor. In the case of an error, a value of –1 is returned. The global variable errno contains the detailed error code.

ERRORS

Returns only Neutrino specific error codes, see Neutrino Library Reference.

SEE ALSO

Library Reference - open()

3.2 close

NAME

close – close a file descriptor

SYNOPSIS

#include <unistd.h>

int close (int filedes)

DESCRIPTION

The close function closes the file descriptor *filedes*.

EXAMPLE

```
int fd;

if (close(fd) != 0)
{
     /* handle close error conditions */
}
```

RETURNS

The normal return value from close is 0. In the case of an error, a value of –1 is returned. The global variable *errno* contains the detailed error code.

ERRORS

Returns only Neutrino specific error code, see Neutrino Library Reference.

SEE ALSO

Library Reference - close()

3.3 devctl

NAME

devctl – device control functions

SYNOPSIS

```
#include <sys/types.h>
#include <unistd.h>
#include <devctl.h>

int devctl
(
        int             filedes,
        int             dcmd,
        void            *data_ptr,
        size_t          n_bytes,
        int             *dev_info_ptr
)
```

DESCRIPTION

The devctl function sends a control code directly to a device, specified by *filedes*, causing the corresponding device to perform the requested operation.

The argument *dcmd* specifies the control code for the operation.

The arguments *data_ptr* and *n_bytes* depends on the command and will be described for each command in detail later in this chapter. Usually *data_ptr* points to a buffer that passes data between the user task and the driver and *n_bytes* defines the size of this buffer.

The argument *dev_info_ptr* is unused for the TPMC500 driver and should be set to NULL.

The following devctl command codes are defined in *tpmc500.h*:

Value	Description
DCMD_TPMC500_READ	Read a new ADC input value
DCMD_TPMC500_CONFIG	Configure the module type
DCMD_TPMC500_SEQ_CONF	Configure channel for sequencer mode
DCMD_TPMC500_SEQ_START	Start sequencer mode
DCMD_TPMC500_SEQ_STOP	Stop sequencer mode

See behind for more detailed information on each control code.

To use these TPMC500 specific control codes, the header file tpmc500.h must be included by the application.

RETURNS

On success, EOK is returned. In the case of an error, the appropriate error code is returned by the function (not in errno!).

ERRORS

Returns only Neutrino specific error codes, see Neutrino Library Reference.

Other function dependent error codes will be described for each devctl code separately. Note, the TPMC500 driver always returns standard QNX error codes.

SEE ALSO

Library Reference - devctl()

3.3.1 DCMD_TPMC500_READ

NAME

DCMD_TPMC500_READ - Read a new ADC input value

DESCRIPTION

This function reads a new ADC input value from a specified channel and returns after conversion of the value to the caller. For this function a *TPMC500_IO_READ_STRUCT* structure must be initialized with appropriate data.

```
typedef struct
{
        int             channel;
        unsigned short  gain;
        long            value;
        long            flags;
} TPMC500_IO_READ_STRUCT;
```

channel

This argument specifies the channel number. Valid channel numbers are 1 up to 32 for single-ended operation mode. For differential mode channel numbers from 1 to 16 are supported.

gain

This argument specifies the used gain level. There are four different gain levels available, the used gain factor depends on the attached TPMC500-module-type. Valid gain levels are:

Value	Resulting Gain Factor	
	TPMC500-x0/-x2	TPMC500-x1/-x3
0	1	1
1	2	2
2	5	4
3	10	8

value

In this argument the new input value will be stored. The input value range depends on the module type and the used gain level (e.g. the use of a TPMC500-10 module with a gain level of 1 (gain factor 2) results in an input-range of ±5V).

flags

This value is an ORed value of the following flags:

Value	Description
TPMC500_CORR_ENA	If this flag is set, the input value will be corrected with the factory stored correction data.
TPMC500_DIFF_MODE	If this flag is set, the differential conversion mode is used for data acquisition.

EXAMPLE

```
#include “tpmc500.h”

int                          fd;
int                          result;
TPMC500_IO_READ_STRUCT       ioBuf;

/*
** read value from channel 1 with correction
*/
ioBuf.channel = 1;
ioBuf.flags   = TPMC500_CORR_ENA;

result = devctl(   fd,
                   DCMD_TPMC500_READ,
                   &ioBuf,
                   sizeof(ioBuf),
                   NULL);
if (result == EOK)
{
     /* command successful */
     printf(“value = %d \n”, iobuf.value);
}
```

ERRORS

Error Code	Description
ECHRNG	Specified channel not supported by attached module.
EINVAL	Invalid gain value specified.
EBUSY	The channel can not be used, because the module is configured in sequencer mode.
ETIME	The module does not complete the conversion cycle within a normal time.

3.3.2 DCMD_TPMC500_CONFIG

NAME

DCMD_TPMC500_CONFIG - Configure the module type

DESCRIPTION

This function is used to tell the driver what type of a TPMC500 module is attached. Therefore a TPMC500_CONFIG_STRUCT structure must be filled with the correct value. The module type must be known for correct calculation of the converted ADC values.

```
typedef struct
{
        int             type;
} TPMC500_ CONFIG_STRUCT;
```

type

This value specifies the attached TPMC500-module-type. The following configuration values are possible (see also header file *tpmc500.h*):

Value	Description
TPMC500_X0	TPMC500-10 / TPMC500-20
TPMC500_X1	TPMC500-11 / TPMC500-21
TPMC500_X2	TPMC500-12 / TPMC500-22
TPMC500_X3	TPMC500-13 / TPMC500-23

EXAMPLE

```
#include “tpmc500.h”

int                             fd;
int                             result;
TPMC500_CONFIG_STRUCT           cfgBuf;

/*
** configure module type
*/
cfgBuf.type = TPMC500_X1;         // e.g. use a TPMC500-11 module

result = devctl(    fd,
                    DCMD_TPMC500_CONFIG,
                    &cfgBuf,
                    sizeof(cfgBuf),
                    NULL);
```

```
if (result == EOK)
{
     /* configuration successful */
}
```

ERRORS

Error Code	Description
EINVAL	Invalid argument. This error code is returned if the specified model-type is invalid.

3.3.3 DCMD_TPMC500_SEQ_CONF

NAME

DCMD_TPMC500_SEQ_CONF - Configures a channel for sequencer mode

DESCRIPTION

This function sets up a channel for use with sequencer mode. For this function the structure *TPMC500_IN_SEQCONF_STRUCT* must be initialized with appropriate data.

```
typedef struct
{
        int             channel;
        unsigned short  gain;
        unsigned short  flags;
} TPMC500_IN_SEQCONF_STRUCT;
```

channel

This argument specifies the channel to be configured. Valid values are 1 to 16/32 depending on the operation mode (differential or single-ended).

gain

This argument specifies the gain level to be used. There are four different gain levels available, the used gain factor depends on the attached TPMC500-module-type. Valid gain levels are:

Value	Resulting Gain Factor	
	TPMC500-x0/-x2	TPMC500-x1/-x3
0	1	1
1	2	2
2	5	4
3	10	8

flags

This value is an ORed value of the following flags:

Value	Description
TPMC500_CORR_ENA	If this flag is set, the input value will be corrected with the factory stored correction data.
TPMC500_DIFF_MODE	If this flag is set, the differential conversion mode is used for data acquisition.
TPMC500_CHAN_ENA	If this flag is set, the specified channel is enabled for sequencer mode. Otherwise it will not be converted during sequencer mode.

EXAMPLE

```
#include “tpmc500.h”

int                          fd;
int                          result;
TPMC500_IN_SEQCONF_STRUCT    seqCfgBuf;

/*
** configure channel 1 for sequencer in single-ended mode, use correction
*/
seqCfgBuf.channel = 1;
seqCfgBuf.gain    = 0;
seqCfgBuf.flags   = TPMC500_CHAN_ENA | TPMC500_CORR_ENA;

result = devctl(   fd,
                   DCMD_TPMC500_SEQ_CONF,
                   &seqCfgBuf,
                   sizeof(seqCfgBuf),
                   NULL);
if (result == EOK)
{
     /* sequencer mode configured */
}
```

ERRORS

Error Code	Description
EINVAL	Invalid gain value specified.

3.3.4 DCMD_TPMC500_SEQ_START

NAME

DCMD_TPMC500_SEQ_START - Start sequencer mode

DESCRIPTION

This function starts the sequencer mode and returns immediately to the caller. The sequencer starts to write its acquired data into a shared memory object defined and opened by the user-application. The data is transferred between the driver and the calling application via the ringbuffer structure defined by TPMC500_RINGBUF. To start the sequencer the structure TPMC500_IN_SEQSTART_STRUCT must be filled with appropriate data.

```
typedef struct
{
        unsigned short      seqTime;
        char                shMemName[15];
} TPMC500_IN_SEQSTART_STRUCT;
```

seqTime

This argument specifies the timer factor used by the sequencer to convert the values from the specified channels. The built-in timer uses a 1/10 ms timeslot, so fixed frequencies up to 10kHz can be specified. If *seqTime* is 0, the sequencer works in runaround-mode, that means after the last conversion of the sequence it starts immediately from the beginning. The sampling frequency depends on the number of channels to be converted.

shMemName

This argument specifies the unique name of the needed shared memory object. It has been limited to 15 characters.

```
typedef struct
{
        int             channel[32];        // value array for each channel
} TPMC500_SEQ_ENTRY;

typedef struct
{
        TPMC500_SEQ_ENTRY buffer[TPMC500_RINGBUF_SIZE];
        unsigned long           putPtr, getPtr;
        char                    status;
} TPMC500_RINGBUF;
```

buffer

This argument specifies the data exchange ringbuffer for data transfer. Only the driver process should write to this memory section. Every buffer entry contains a data storage for one complete sequence (32 values). To change the ringbuffer size, edit the value of TPMC500_RINGBUF_SIZE defined in the header file *tpmc500.h*.

The driver and the example must be recompiled and restarted after changing *TPMC500_RINGBUF_SIZE*.

putPtr

This argument specifies the position where the driver will fill in the next acquired value. After the new sequence values were written to the buffer, *putPtr* will be set to the next location.

getPtr

This argument specifies the position where the application can read a new value. After the read-operation the application has to increase the *getPtr*-value to get to the next read-position. It is necessary to use this value out of the shared memory object because the driver has to know the current reading position to avoid overwriting data.

status

This argument describes the actual status of the sequencer. Possible values are as follows:

Value	Description
TPMC500_SEQ_OK	Sequencer is working fine, no errors.
TPMC500_SEQ_ERR_TIMER	The specified timer value is too small for all channels to finish conversion.
TPMC500_SEQ_ERR_SW_DATA_OF	The ringbuffer is full, the driver cannot write new values, data is lost. The reading from the buffer was too slow.
TPMC500_SEQ_ERR_HW_DATA_OF	The TPMC500-module signals a hardware buffer overflow. The driver has not fetched the new values from the sequencer RAM.

EXAMPLE

```
#include “tpmc500.h”

int                          fd, sharedmemfd;
int                          result;
TPMC500_IN_SEQSTART_STRUCT   seqStartBuf;
TPMC500_RINGBUF              *pRingBuf;

/*
** initialize shared memory object. don’t forget to handle errors!
*/
sharedmemfd = shm_open(SHARED_MEMORY_NAME, O_RDWR | O_CREAT, 0777);
ftruncate(sharedmemfd, sizeof(TPMC500_RINGBUF));
pRingBuf = mmap( 0, sizeof(TPMC500_RINGBUF),
                 PROT_READ | PROT_WRITE, MAP_SHARED, sharedmemfd, 0);

/*
** start sequencer mode with a 10 * 1/10 ms timer factor
*/
seqStartBuf.seqTime   = 10;
seqStartBuf.shMemName = “/ringbuffer”;

result = devctl(   fd,
                   DCMD_TPMC500_SEQ_START,
                   seqStartBuf,
                   sizeof(seqStartBuf),
                   NULL);
if (result == EOK)
{
     /* sequencer successfully started */

     /** see example application and “Programming Hints” for read method */
}
```

ERRORS

Error Code	Description
ENOBUFS	Open of shared memory object failed.
ENOSPC	Setting the size for the shared memory object failed.
EACCES	Mapping of the shared memory object failed.
ETIME	Sequencer refused to start within specific timeout.

3.3.5 DCMD_TPMC500_SEQ_STOP

NAME

DCMD_TPMC500_SEQ_STOP - Stop sequencer mode

DESCRIPTION

This function stops the sequencer mode, no options have to be supplied. It returns immediately to the caller.

EXAMPLE

```
#include “tpmc500.h”

int                         fd;
int                         result;

/*
**  stop sequencer mode
*/

result = devctl(   fd,
                   DCMD_TPMC500_ SEQ_STOP,
                   NULL,
                   0,
                   NULL);
if (result == EOK)
{
     /* sequencer stop successful */
}
```

ERRORS

Error Code	Description
ETIME	The sequencer refused to stop within specific timeout.

4 Programming Hints

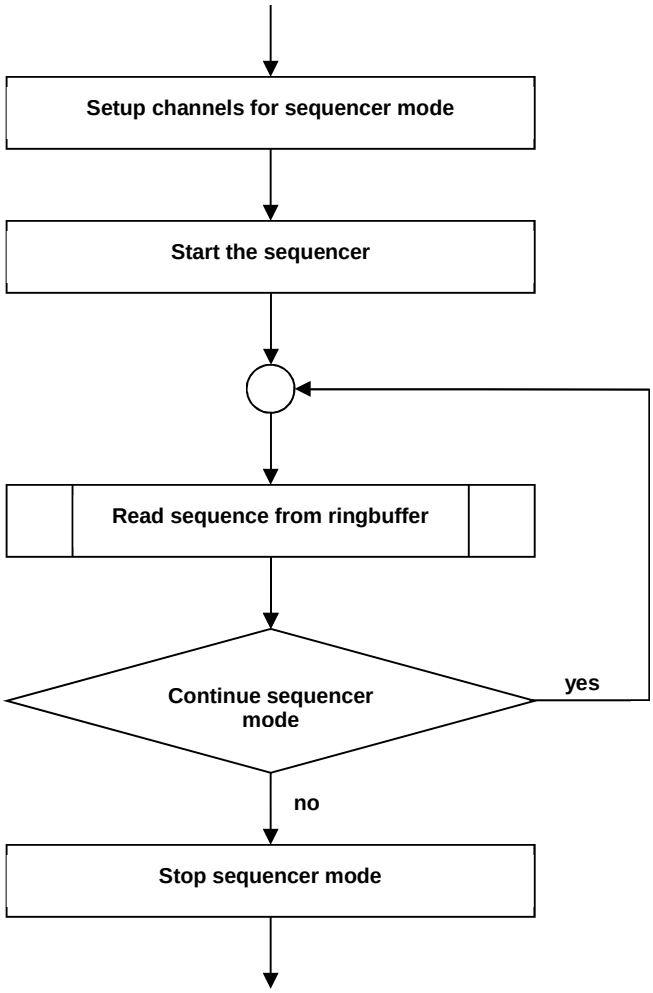
4.1 Using the Sequencer Mode

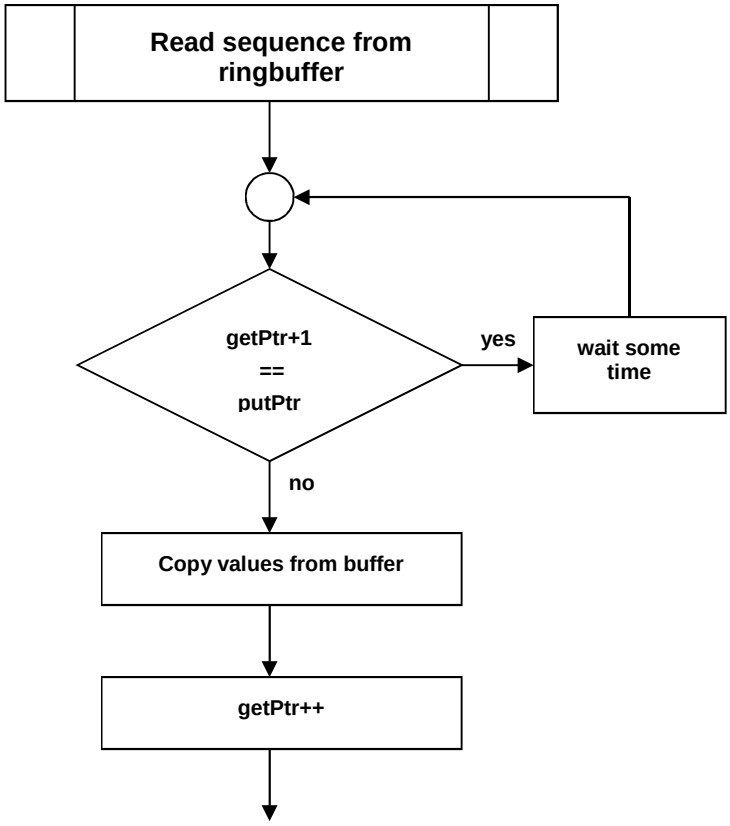
The following flow-charts are describing the high-performance sequencer mode. Because of the shared-memory usage no task-switching overhead slows down the data acquisition and transfer from the driver to the application.

For information about the achievable acquisition frequency, please refer to the TPMC500 hardware user manual.

Make sure that the application reads the data fast enough. Do not try to print the acquired data on the screen via *printf* in a high frequency application. Use a file stream instead for debugging.

Note that for every completed sequencer cycle an interrupt is generated by the TPMC500 handled by the driver!




Read sequence from ringbuffer
getPtr+1 == putPtr
yes
wait some time
no
Copy values from buffer
getPtr++